

DigiTRAK[®] ECLIPSE[®]

inGround Positioning System (iGPS[®])

Operator's Manual



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Limited Warranty

All products manufactured and sold by DCI are subject to the terms of a Limited Warranty. A copy of the Limited Warranty is included with this manual along with your DigiTrak[®] Eclipse[®] Locating System; it can also be obtained by contacting DCI Customer Service, 800-288-3610 or 425-251-0559, or by connecting to DCI's web site, www.digitrak.com.

Important Notice

All statements, technical information, and recommendations related to the products of Digital Control Incorporated (DCI) are based on information believed to be reliable, but the accuracy or completeness thereof is not warranted. Before utilizing any DCI product, the user should determine the suitability of the product for its intended use. All statements herein refer to DCI products as delivered by DCI and do not apply to any user customizations not authorized by DCI nor to any third-party products. Nothing herein shall constitute any warranty by DCI nor will anything herein be deemed to modify the terms of DCI's existing Limited Warranty applicable to all DCI products.

FCC Compliance Statement

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the Rules of the Federal Communications Commission. These limits are designed to provide reasonable protection against harmful interference in a horizontal directional drilling installation. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications or inaccurate readings on your DCI locating equipment. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the DigiTrak[®] Eclipse[®] Receiver.
- Increase the separation between the problematic equipment and the DigiTrak[®] Eclipse[®] Receiver.
- Connect the equipment into an outlet on a different circuit.
- Consult the dealer for help.

Changes or modifications to the DCI equipment not expressly approved and carried out by DCI will void the user's Limited Warranty and the FCC's authorization to operate the equipment.

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Safety Precautions and Warnings

Important Note: All operators must read and understand the following Safety Precautions and Warnings and must review this *Operator's Manual* before using the DigiTrak[®] Eclipse[®] Locating System.

☠ Serious injury and death can result if underground drilling equipment makes contact with an underground utility such as a high-voltage electrical cable or a natural gas line.

➡ Substantial property damage and liability can result if underground drilling equipment makes contact with an underground utility such as a telephone, cable TV, fiber-optic, water, or sewer line.

🕒 Work slowdowns and cost overruns can occur if drilling operators do not use the drilling or locating equipment correctly to obtain proper performance.

- Directional drilling operators **MUST** at all times:
 - Understand the safe and proper operation of drilling and locating equipment, including the use of ground mats and proper grounding procedures.
 - Ensure that all underground utilities have been located, exposed, and marked accurately prior to drilling.
 - Wear protective safety clothing such as dielectric boots, gloves, hard-hats, high-visibility vests and safety glasses.
 - Locate and track the drill head accurately and correctly during drilling.
 - Comply with state and local governmental regulations (e.g., OSHA).
 - Follow all other safety procedures.
- The DigiTrak Eclipse system cannot be used to locate utilities.
- Continued exposure to heat, due to frictional heating of the drill head, can cause inaccurate information to be displayed and may permanently damage the transmitter.

⚠ The DigiTrak Eclipse equipment is not explosion-proof and should never be used near flammable or explosive substances.

Safety Precautions and Warnings (Continued)

- Before each drilling run, test the DigiTrak Eclipse system to confirm that it is operating properly and check that it is providing accurate drill head location and heading information and accurate drill head depth, pitch, and roll information with the transmitter inside the drill head.
- During drilling, the depth will not be accurate unless:
 - The Eclipse receiver has been properly calibrated and the calibration has been checked for accuracy so that the receiver shows the correct depth.
 - The drill head has been located correctly and accurately and the receiver is directly above and parallel to the transmitter in the tool underground or above the front locate point (FLP).
 - The receiver height-above-ground or ultrasonic distance has been set correctly.
- Interference can cause inaccuracies in the measurement of depth and loss of pitch, roll, or the transmitter's location or heading.
 - Sources of interference include but are not limited to traffic signal loops, invisible dog fences, cable TV, power lines, fiber-trace lines, metal structures, cathodic protection, telephone lines, cell phones, transmission towers, conductive earth, salt water, rebar, radio frequencies, and other unknown sources of interference.
 - Interference with the operation of the remote display may also occur from other sources operating nearby on the same frequency, such as car rental agencies using their remote check-in modules, other directional drilling locating equipment, etc.
- Carefully review this *Operator's Manual* and be sure you always operate the DigiTrak Eclipse system properly to obtain accurate depth, pitch, roll, and locate points. If you have any questions about the operation of the DigiTrak System, please call DCI's Customer Service Department at 425-251-0559 or 800-288-3610.

REMEMBER

If you are having difficulty on the job, call DCI (425-251-0559 or 800-288-3610) and we'll attempt to help you solve the problem.

Introduction



DigiTrak Eclipse InGround Positioning System

The DigiTrak® Eclipse® inGround Positioning System (iGPS®) brings a new level of locating ease to the operator of horizontal directional drilling (HDD) locating equipment. The new *target-in-the-box*® locating feature and *look-ahead*® capability enable Intuitive® tracking of the transmitter. The menu options provide quick verification of mode settings and also the ability to program the intended position of the transmitter for easier remote steering—this is DCI's new *Target Steering*® feature.

The DigiTrak Eclipse locating system uses different transmitting frequencies than other DigiTrak locating systems. These frequencies reduce the effects of interference and increase locating efficiency.

This manual provides operating instructions for the DigiTrak Eclipse locating system. The information is presented in sections as follows:

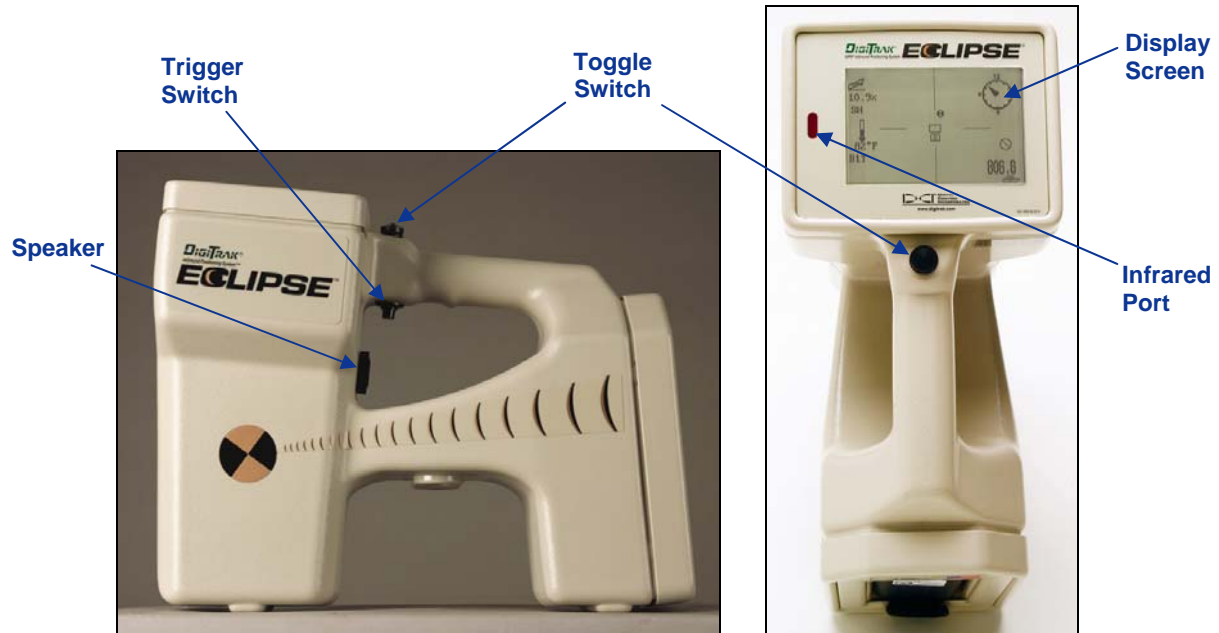
- Receiver
- Remote Display
- Transmitter
- Battery Charger
- Locating
- The *Target Steering* Function

- Cable System
- Troubleshooting

The first four sections describe and explain how to use the main components: the receiver, the remote display, the transmitter, and the battery charger. The next two sections give instructions for using the system for locating and for steering to a target. These are followed by a description of and instructions for using the Eclipse cable transmitter system. The final section provides quick-reference troubleshooting information. An appendix is also included with reference tables.

NOTE: Be sure to read carefully the *Safety Precautions and Warnings* section at the front of this manual before you use the equipment.

Receiver



Eclipse Receiver Side View (left) and Top View (right)

Power On

Before turning the Eclipse receiver on, place the DCI NiCad battery pack (with terminals exposed to the receiver's springs) into the battery compartment at the back end of the receiver. Then, click the trigger under the handle (push it in and release it in less than ½ second) to power up the Eclipse receiver. It may take a moment for the display to appear.

Toggle and Trigger Switches

The Eclipse receiver has two types of switches for operating the system—a toggle (thumb switch) and a trigger. The toggle switch is located on top of the handle. It moves in four different directions—left, right, up, and down. Push the toggle left or right to move the menu arrows on the display to select the desired menu item. Push the toggle up or down once a menu item is selected to change specific settings, such as the channel setting.

The trigger switch is located under the handle. It is used to access a menu item once it has been selected with the toggle. To access the selected menu item, click the trigger (push it in and release it in less than ½ second). When the receiver is in locate mode, the trigger can be held in to view the depth or predicted depth reading.

Speaker and Audible Tones

The receiver has a speaker below the trigger area of the handle. The speaker emits warning tones if the transmitter's temperature is increasing to indicate that appropriate and immediate attention is required.

Adjusting Screen Contrast

There are two techniques for adjusting the display screen contrast to gradually lighten or darken it. The receiver must be in locate mode for either technique.

- Hold in the trigger while pushing the toggle several times to the right (to lighten) or to the left (to darken) the display's contrast.
- Push and hold the toggle to the right (to lighten) or to the left (to darken) while clicking the trigger for the desired contrast.

NOTE: The remote display screen is adjusted in the same way as the receiver except the execute button serves as the trigger and the toggle arrows work in the same manner as the toggle switch (see *Remote Display* section in this manual).

Main Menu

The main system display for the Eclipse software shows the current date/time, the CPU version, and the DSP version when the unit is first turned on (an example is shown in the figure below). It also shows the main menu options—**Locate**, **Power Off**, **Set US**, **Configure**, and **Low Fre/High Fre** (this option can be viewed by toggling right past **Configure**). When an item is selected with the toggle, it is indicated by arrows on the right and left, as shown in the figure below where the **Locate** menu is selected.



Receiver Main Menu Display

To access one of the main menu items, select the item and then click the trigger once. To select the **Low Fre/High Fre** menu option, you must toggle right past the **Configure** menu. The result for each menu item is shown in the table below.

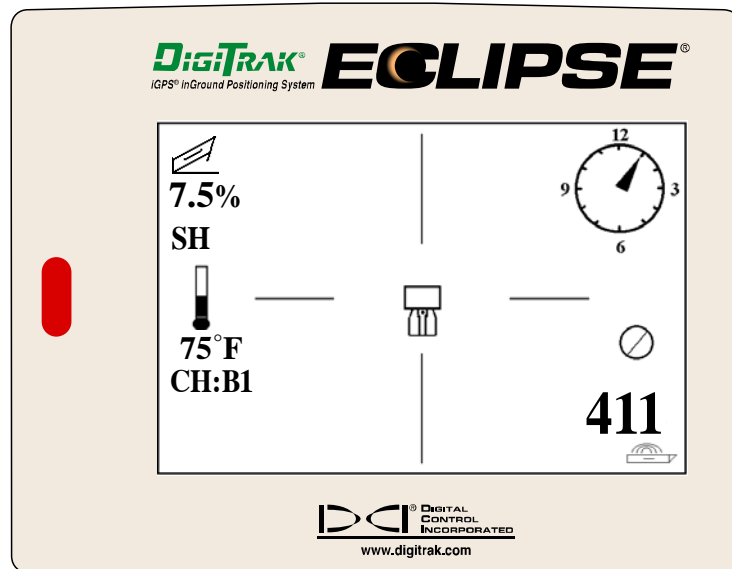
Receiver Main Menu Options

Locate	Displays the locate mode screen (see “Locate Menu” section below). This screen gives a bird's-eye view showing the transmitter's position (see the <i>Locating</i> section in this manual). It also provides information such as battery status, temperature, roll, pitch, and signal strength. If the receiver is over the locate line (LL) and the trigger is held in, the depth is shown; if over the front locate point (FLP), the predicted depth is shown.
Power Off	Turns off the Eclipse receiver. Use the toggle to select Power Off , then click the trigger.
Set US	Sets the ultrasonic (US) height setting, which is the height of the receiver above the ground. See “Set US Menu” section below.
Configure	Presents another set of menu options. See the “Configure Menu” section for an explanation of the Configure menu options.
Low Fre / High Fre	<p>Changes the receiver's frequency setting—for use with the dual-frequency transmitter. See “Low Fre/High Fre Menu” provided below before the “Configure Menu” section.</p> <p>NOTE: The frequency setting displayed at the main menu is actually <i>asking</i> if you want to change to that setting. For example, if you see Low Fre, then the receiver is set to receive high-frequency signals, and clicking on Low Fre will change the receiver setting to low frequency. If you see High Fre, then the receiver is set to receive low-frequency signals, and clicking will change the setting to high frequency.</p> <p>For more information on the operation of the dual-frequency transmitter, see the sections entitled “Starting the Transmitter in Dual- and Single-Frequency Modes” later in this section and in the <i>Transmitter</i> section.</p>

Locate Menu

Accessing Locate Mode

- From the main menu screen, push the toggle down once or toggle left to select **Locate**, then click the trigger. You will see the locate mode screen.
- From any screen other than the main menu, push down twice on the toggle to advance to the **Locate** menu, then click the trigger to enter the locate mode. You will see the locate mode screen.



Locate Mode Screen

Displaying Depth (From the Locate Screen)

1. From the locate mode, hold in the trigger—the depth or predicted depth of the transmitter will be displayed. You will also see the ultrasonic height setting and the battery status of the receiver and the transmitter.
2. Release the trigger and you will be returned to the locate mode screen.

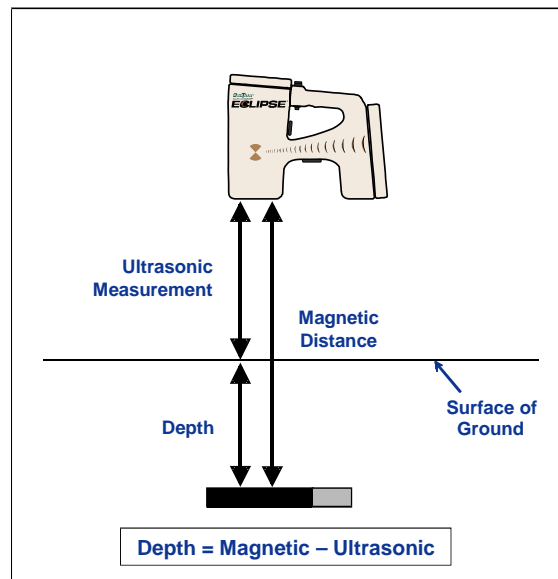
NOTE: You will only see depth (or predicted depth) while at the FLP, RLP, or on the LL (see the *Locating* section for information on the FLP, RLP, and LL).

Exiting Locate Mode and Returning to Main Menu

From the locate mode, push the toggle down once to return to the main menu.

Set US Menu

The ultrasonic (US) function measures the receiver's height above the ground. This distance is then subtracted from the total magnetic distance from the receiver to the transmitter to determine the depth of the transmitter below the ground's surface (see figure below).



Use of Ultrasonic Measurement to Determine Actual Depth

Changing the Ultrasonic Setting

1. Select **Set US** from the main menu, position the receiver at the desired height above the ground, and click the trigger one time. The display will show the new ultrasonic setting.

NOTE: You must have the US setting at "0" if are placing the receiver on the ground to take depth readings.

2. When you are satisfied with the US setting, toggle down once to return to the main menu.

Viewing the Ultrasonic Setting

From the locate mode screen, hold in the trigger to view the US setting. The US setting can be viewed at any time during locating (see *Locating* section).

Low Fre/High Fre Menu

Frequency Settings

The frequency menu option will display as either **Low Fre** (low frequency) or **High Fre** (high frequency).

If you see **Low Fre**, you are being *asked* if you would like to change to the low-frequency setting; this means the receiver is set to receive high-frequency (12-kHz) signals. If you are running the standard Eclipse transmitter (black tube), the Eclipse dual-frequency transmitter (lavender tube) in single-high (SH) or dual-high (DH) mode, or the mini transmitter (gray tube), the receiver should display **Low Fre**.

If you see **High Fre**, you are being *asked* if you would like to change to the high-frequency setting, which means the receiver is currently set to receive low-frequency signals. If you are running the dual-frequency transmitter in dual-low (DL) mode, the receiver should display **High Fre**.

NOTE: The only time you should see **High Fre** is when you are using the dual-frequency transmitter in dual-low (DL) mode. For additional information, see the *Transmitter* section.

Changing the Frequency Setting

To change the frequency setting, select the frequency option that is shown, and click the trigger.

Configure Menu

The **Configure** menu options are listed and described briefly in the table given below. More detailed information and instructions for each menu option follow this listing.

Most of the menu options are presented as a question. For example, if you see ° **Grade** you are being asked, “Do you want to measure pitch in degrees?” If the answer is yes, then click the trigger. The menu item will then change to show % **Grade**.

Receiver Configure Menu Options

Tele Ch.	Changes the telemetry channel setting for the receiver to communicate with the remote display at the drill (see “Changing the Telemetry Channel” section). NOTE: The receiver must be set to the same channel as the remote display. The channel setting is displayed on the lower left side of the locate screen.
1 Pt. Cal.	Initiates standard calibration procedure used with the transmitter above ground (see “1-Point Calibration” section).
2 Pt. Cal.	Initiates calibration procedure used when the transmitter is below ground (see “2-Point Calibration” section). Should be used with caution.
Target Depth	Allows you to program the transmitter’s depth at a prescribed distance ahead of its current location. Used for <i>Target Steering</i> function (see <i>The Target Steering Function</i> section later in this manual).
° Grade / % Grade	Changes how the transmitter’s pitch information is displayed (see “Changing the Grade Mode” section). The pitch can be displayed in percent slope (%) or in degrees (°).
Use Metric / Use English	Changes the depth measurement mode (see “Changing the Depth Measurement Mode” section). The depth can be displayed in metric units or in three forms of English units (IN Only , FT Only , or FT/IN Units). When measuring depth in metric units, the transmitter temperature is displayed in °C; when measuring in English units, the transmitter temperature is displayed in °F.
IN Only / FT Only / FT/IN Units	Changes the English units for the depth setting. Selecting IN Only will display the depth in inches and change the menu option to show FT Only . Selecting FT Only will display the depth in feet and will change the menu option to show FT/IN Units . Selecting FT/IN Units will display depth in feet and inches and will change the menu option to show IN Only . All these depth measurement options display the temperature in °F.
Cold Screen / Normal Screen	Changes from one contrast mode to the other—the screen can have a black (cold) background or a light (normal) background (see “Cold/Normal Screen” section).
Tele Option A/B	Allows communication from a receiver to a remote display when they have different telemetry systems, such as when one unit has TeleLock™ Technology or TLT and the other does not (see “Changing the Telemetry Channel” and “Tele Option A/B” sections).
Locator DL / No Locator DL	Enables the DataLog Mapping System menu options so that you can access DataLog functions from the Eclipse receiver’s main menu screen and store data when locating (see “Locator DL / No Locator DL” section).
Set Roll / Unset Roll	Enables the roll offset function, which allows the transmitter’s roll position to be compensated to match the tool’s roll position (see “Set Roll / Unset Roll” section).
Code	This menu option is provided for DCI to use for calibration during manufacturing and for diagnosing problems for repairs.
Exit	Returns display to the main menu screen.

Changing the Telemetry Channel

Telemetry is the wireless communication system used between the receiver and the remote display. The receiver must be set to the same telemetry channel as the remote display at the drill. There are five channel settings, including a setting of zero. There are actually only two frequencies—channels 1 and 3 operate at the same frequency, and channels 2 and 4 operate at the same frequency. The zero setting will not send a signal, and it will also conserve the NiCad battery life in the receiver.

To change the telemetry channel:

1. Select **Configure** from the main menu screen, and click the trigger.
2. Select **Tele Ch.**, and click the trigger. The current channel setting will be displayed.
3. Push the toggle up to advance the channel setting or pull the toggle down to decrease the channel setting.

NOTE: The receiver must be set to the same channel as the remote display.

4. Once the desired channel is displayed, click the trigger.
5. To exit and return to the main menu, push the toggle down one time.

In addition to the telemetry channel settings, you may need to use the **Tele Option A/B** function. This function is part of DCI's most advanced telemetry system called TeleLock™ Technology (TLT). TLT extends the telemetry range for longer bores and when the line of sight between the receiver and remote display is compromised.

You must use the Tele Option A/B function on the receiver to display Tele Option B (which means it is set to Tele Option A) when operating a newer TLT receiver (serial number equal to or greater than EDRR 2690) and an older remote display (serial number less than EDD 2644). If you are operating an older receiver (serial number less than EDRR 2690) with a newer remote display (serial number equal to or greater than EDD 2644), then you must use the Tele Option A/B function on the remote display to show Tele Option B (see "Tele Option A/B" later in this section).

When using a newer receiver with TLT and an older remote display without TLT, you must change the Tele Option A/B setting on the receiver to show Tele Option B:

1. Select **Configure** from the main menu screen, and click the trigger.
2. Toggle to the right several times to select **Tele Option A**, and click the trigger. **Tele Option B** will now display, and this newer TLT receiver will now communicate with the older remote display.

When using an older receiver without TLT and a newer remote display with TLT, you must change the Tele Option A/B setting on the remote display to show Tele Option B:

1. Select **Configure** from the main menu screen, and press the execute button.
2. Press the right arrow several times to select **Tele Option A**, and press the execute button. **Tele Option B** will now display, and this newer TLT remote display will now communicate with the older receiver.

You can upgrade your Eclipse receiver and remote display units to have the TLT or enhanced telemetry function. If you are interested in doing so, please call DCI (425-251-0559 or 800-288-3610) to discuss.

For additional telemetry range, contact DCI to discuss alternate antenna options for your remote display.

1-Point Calibration

The 1-point calibration procedure is performed with the transmitter in the housing parallel to and 10 ft (3 m) from the receiver, as described below. DCI does not recommend calibrating every day, but you should verify the receiver's depth readings at several locations using a tape measure.

Calibration is necessary prior to first-time use and when any of the following occur:

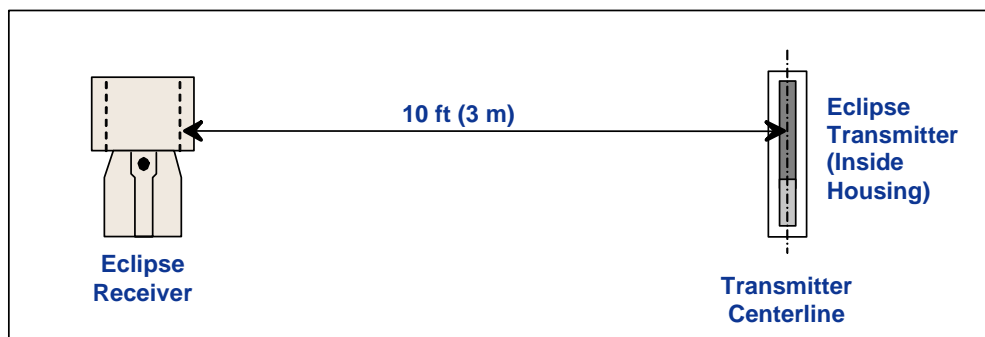
- The transmitter is changed.
- The receiver is changed.
- The housing/drill tool is changed.

Do not calibrate if:

- You are within 10 ft (3 m) of metal structures, such as steel pipe, chain link fence, metal siding, construction equipment, or automobiles.
- The receiver is over rebar or underground utilities.
- The receiver is in the vicinity of excessive electrical interference.
- The transmitter is not installed into the housing.
- The transmitter is not turned on.

1-Point Calibration for Standard and Mini Eclipse Transmitters

1. Power up the Eclipse receiver.
2. Toggle right past the **Configure** menu to verify that you see **Low Fre** on the main menu screen. If you see **High Fre**, then select it, and click the trigger so that the menu option will change to **Low Fre**.
3. Select **Locate**, and click the trigger.
4. Power up the standard or mini transmitter, and place it into the housing. Verify that the transmitter is sending proper pitch, roll, battery, and temperature status information.
5. With the transmitter in the housing, measure 10 ft (3 m) from the centerline of the transmitter to the bottom inside edge of the receiver below the display window (see figure)—this should be measured to the bottom inside edge of the receiver where it meets the ground, not the upper edge at the display, which is wider.



10-Foot Measurement for 1-Point Calibration

6. Verify that the signal strength at 10 ft (3 m) is approximately 528 for the standard transmitter, or 360 to 370 for the mini transmitter, and record the value.
7. Select **Configure** on the main menu display, and click the trigger.

8. Toggle right to the **1 Pt. Cal.** menu item, and click the trigger.
9. Select **High Fre Cal**, and click the trigger.
10. Toggle to select **Y** for yes, and click the trigger.
11. Follow the instructions on the display, and click the trigger appropriately.
12. To exit the calibration function and return to the main menu, push the toggle down two times.
13. To access the locate mode, push the toggle to the left until **Locate** is selected or push the toggle down one time, and then click the trigger.
14. Verify that the depth reading at 10 ft (3 m) reads 10 ft (3 m); this requires you to go into locate mode and then hold in the trigger. Check the depth readings in two other locations (e.g., 5 ft/1.5 m and 15 ft/4.6 m).

1-Point Calibration for Eclipse Dual-Frequency Transmitter

To calibrate the Eclipse dual-frequency transmitter (lavender tube), you must first understand how this type of transmitter works.

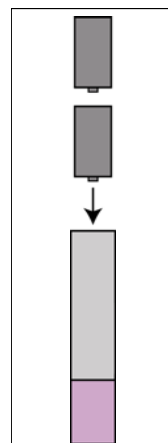
The dual-frequency transmitter can be set to transmit in two different modes—dual-frequency mode (transmitting at 1.5 kHz and 12 kHz) or single-frequency mode (transmitting at 12 kHz). When the dual-frequency transmitter is started up in dual mode, the transmitter is actually sending signals at both frequencies. The receiver must be set to detect the correct signal or signals being transmitted by the transmitter.

Each frequency mode offers specific advantages. The dual-frequency mode provides a depth range of approximately 40 ft (12.2 m) at either the low (1.5 kHz) or high (12 kHz) frequency. This mode is recommended in areas where rebar, wire mesh, or other metal (passive) interference may be encountered. The single-frequency mode (12 kHz only) provides a depth range of approximately 60 ft (18.3 m). This mode is intended for use in areas of active interference.

The frequency mode for the transmitter is determined by the orientation of the transmitter at startup, when the batteries are loaded into the battery compartment. You cannot change the frequency mode of the dual-frequency Eclipse transmitter when it is downhole.

Starting the transmitter in dual-frequency mode

1. Remove the battery cap, and hold the transmitter vertically with the battery compartment up and the front end pointing down (see diagram).
2. Load two C-cells (or a SuperCell lithium battery) into the battery compartment with the positive terminal down.
3. Replace the battery cap while rotating the transmitter in this vertical position.
4. Power up the receiver, and verify that the main menu option shows **High Fre.**
5. Select **Locate**, and click the trigger.
6. You will see **DL** for Dual Low on the left side of the screen directly above the thermometer symbol.
7. Verify that the signal strength in the housing at a distance of 10 ft (3 m) is 480 to 490, and record the value.



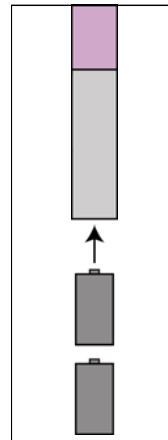
**Loading Batteries
for Dual Mode**

To track the transmitter in dual-high mode, if there is no metal interference:

1. Return to the main menu screen, select **High Fre** from the main menu, and click the trigger.
2. Select **Locate**, and click the trigger.
3. You will see **DH** for Dual High on the left side of the screen, directly above the thermometer symbol.
4. Verify that the signal strength in the housing at a distance of 10 ft (3 m) is 520 to 530, and record the value.

Starting the transmitter in single-frequency mode

1. Remove the battery cap, and hold the transmitter vertically with the battery compartment down and the front end pointing up (see diagram).
2. Load two C-cells (or a SuperCell lithium battery) into the battery compartment with the positive terminal entering first.
3. Replace the battery cap while rotating the transmitter in this vertical position.
4. Power up the receiver, and verify that the main menu option shows **Low Fre**.
5. Select **Locate**, and click the trigger.
6. You will see **SH** for Single High on the left side of the screen directly above the thermometer.
7. Verify that the signal strength in the housing at a distance of 10 ft (3 m) is approximately 565, and record the value.



**Loading Batteries
for Single Mode**

Calibrating the receiver to the dual-frequency transmitter in dual-frequency mode

The following instructions will require you to perform two calibration procedures—once for low frequency and once for high frequency.

1. Start up the dual-frequency transmitter in dual-frequency mode (see instructions above), and place it in the housing.
2. Power up the receiver.
3. Verify that you see **Low Fre** on the main menu display (toggle right past **Configure**). If you see **High Fre**, select **High Fre**, and click the trigger. The display will then change to show **Low Fre** (which means the receiver is detecting the transmitter's high-frequency signal).
4. With the transmitter in the housing, measure 10 ft (3 m) from the centerline of the transmitter to the bottom inside edge of the receiver below the display window (see figure above entitled "10-Foot Measurement for 1-Point Calibration")—this should be measured to the bottom inside edge of the receiver where it meets the ground, not the upper edge at the display, which is wider.
5. Verify that the signal strength at 10 ft (3 m) is approximately 530 to 540, and record the value (this requires you to go into locate mode; the signal strength is near the bottom of the screen).
6. Verify that the transmitter is sending proper pitch, roll, battery, and temperature status information (pitch and roll are viewed from the locate mode screen; battery and temperature status are viewed from the depth display screen—see the *Locating* section).

7. Return to the main menu screen by pushing the toggle down one time.
8. Select **Configure** on the main menu display, and click the trigger.
9. Select **1 Pt. Cal.**, and click the trigger.
10. Click the trigger (arrows will have already selected **High Fre Cal**).
11. Toggle right to select **Y** for yes, and click the trigger.
12. Follow the instructions on the display, and click the trigger appropriately.
13. Return to the main menu by pushing the toggle down two times.
14. Select **Locate**, and click the trigger.
15. Place the receiver at 10 ft (3 m) and verify that it reads 10 ft (3 m) by holding in the trigger. Check the depth readings in two other locations (e.g., 5 ft/1.5 m and 15 ft/4.6 m).
16. You will now calibrate in low frequency. First, select **Low Fre** from the main menu screen, and click the trigger.
17. Select **Configure**, and click the trigger.
18. Select **1 Pt. Cal.**, and click the trigger.
19. Select **Low Fre Cal**, and click the trigger.
20. Follow the instructions on the display, and click the trigger appropriately.
21. Return to the main menu by pushing the toggle down two times.
22. Select **Locate**, and click the trigger.
23. Place the receiver at 10 ft (3 m) and verify that it reads 10 ft (3 m) by holding in the trigger. Check the depth readings in two other locations (e.g., 5 ft/1.5 m and 15 ft/4.6 m).

Calibrating the receiver to the dual-frequency transmitter in single-frequency mode

This procedure is the same as that for calibrating a standard or mini Eclipse transmitter using 1-point calibration.

1. Start up the dual-frequency transmitter in single-frequency mode (see instructions above), and place it in the housing. Verify that the transmitter is sending proper pitch, roll, battery, and temperature status information.
2. Power up the receiver.
3. Select **Low Fre** on the main menu display (toggle right past **Configure**), and click the trigger. The display will then change to show **Low Fre** (which means the receiver is detecting the transmitter's high-frequency signal).
4. With the transmitter in the housing, measure 10 ft (3 m) from the centerline of the transmitter to the bottom inside edge of the receiver below the display window (see figure above entitled "10-Foot Measurement for 1-Point Calibration")—this should be measured to the bottom inside edge of the receiver where it meets the ground, not the upper edge at the display, which is wider.
5. Verify that the signal strength at 10 ft (3 m) is approximately 565, and record the value (this requires you to go into locate mode; the signal strength is near the bottom of the screen).

6. Return to the main menu screen by pushing the toggle down one time.
7. Select **Configure** on the main menu display, and click the trigger.
8. Select **1 Pt. Cal.**, and click the trigger.
9. Click the trigger (arrows will have already selected **High Fre Cal**).
10. Toggle right to select **Y** for yes, and click the trigger.
11. Follow the instructions on the display, and click the trigger appropriately.
12. Return to the main menu by pushing the toggle down two times.
13. Select **Locate**, and click the trigger.
14. Place the receiver at 10 ft (3 m) and verify that it reads 10 ft (3 m) by holding in the trigger. Check the depth readings in two other locations (e.g., 5 ft/1.5 m and 15 ft/4.6 m).

2-Point Calibration (In-ground Calibration)

NOTE: In-ground calibration is rarely needed. If you must calibrate with the transmitter in the ground, use this procedure with caution.

2-Point Calibration for Standard, Mini, and Long-Range Transmitters

To calibrate the receiver using the 2-point calibration method with the standard, mini, or long-range transmitter in the ground:

1. Verify that you see **Low Fre** on the main menu screen. If you see **High Fre**, then select it and click the trigger so that the menu option will change to **Low Fre**.
2. Select **Configure**, and click the trigger.
3. Select **2 Pt. Cal.**, and click the trigger.
4. Select **High Fre Cal**, and click the trigger.
5. Toggle to select **Y** for yes, and click the trigger.
6. Position and stabilize the receiver at least 6 in. (152 mm) above the ground directly over the transmitter; be sure that the locate line (LL) is aligned with the horizontal cross hairs to ensure you are directly over the transmitter (refer to the *Locating* section for details on the LL).
7. Click the trigger when the display instructions indicate.
8. Raise the receiver at least 30 in. (762 mm) and stabilize it, then click the trigger.
9. To exit the calibration function and return to the main menu, push the toggle down two times.

2-Point Calibration for Eclipse Dual-Frequency Transmitter

To calibrate the receiver using the 2-point calibration method with the dual-frequency transmitter in the ground, you will perform two calibration procedures—the first for low frequency and the second for high frequency.

The first calibration procedure is for high frequency:

1. Verify that you see **Low Fre** on the main menu screen. If you see **High Fre**, then select it and click the trigger so that the menu option will change to **Low Fre**.
2. Select **Configure**, and click the trigger.
3. Select **2 Pt. Cal.**, and click the trigger.
4. Select **High Fre Cal**, and click the trigger.
5. Toggle to select **Y** for yes, and click the trigger.
6. Position and stabilize the receiver at least 6 in. (152 mm) above the ground directly over the transmitter; be sure that the locate line (LL) is aligned with the horizontal cross hairs to ensure you are directly over the transmitter (refer to the *Locating* section for details on the LL).
7. Click the trigger when the display instructions indicate.
8. Raise the receiver at least 30 in. (762 mm) and stabilize it, then click the trigger.
9. To exit the calibration function and return to the main menu, push the toggle down two times.
10. Verify depth readings by going into locate mode.

The second calibration procedure is for low frequency:

1. Select **Low Fre** from the main menu screen, and then click the trigger to change this option to display **High Fre**.
2. Select **Configure**, and click the trigger.
3. Select **2 Pt. Cal.**, and click the trigger.
4. Select **Low Fre Cal**, and click the trigger.
5. Toggle to select **Y** for yes, and click the trigger.
6. Position and stabilize the receiver at least 6 in. (152 mm) above the ground directly over the transmitter; be sure that the locate line (LL) is aligned with the horizontal cross hairs to ensure you are directly over the transmitter (refer to the *Locating* section for details on the LL).
7. Click the trigger when the display instructions indicate.
8. Raise the receiver at least 30 in. (762 mm) and stabilize it, then click the trigger.
9. To exit the calibration function and return to the main menu, push the toggle down two times.
10. Verify depth readings by going into locate mode.

Changing the Grade Mode

The **Grade** menu item will display as either ° **Grade** or % **Grade**. If you see ° **Grade**, you are being asked if you would like the pitch measured in degrees. If your answer is yes, click the trigger. This menu option will then change to display % **Grade**. If you do not click the trigger when you see ° **Grade**, you will continue to measure pitch in percent slope.

To change the grade measurement mode:

1. Select **Configure**, and click the trigger.
2. Select **Grade**, and click the trigger. Either ° **Grade** or % **Grade** will be displayed, depending on which measurement mode you are in. If you are measuring in percent slope, you will see ° **Grade** (giving you the option to change to degrees); if you are measuring in degrees, then you will see % **Grade**.

Changing the Depth Measurement Mode

The depth measurement mode can be changed from metric (meters) to English, and in English it can be displayed in feet and inches (**FT/IN Units**), in feet only (**FT Only**), or in inches only (**IN Only**). Remember, whichever depth measurement mode option you see, it means you are being asked if you would like to change to that mode—it does not mean that is the mode you are currently measuring depth in.

To change the depth measurement mode:

1. Select **Configure**, and click the trigger.
2. Select one of the following:
 - **Use English** to display depth measurements in English units
 - **Use Metric** to display depth measurements in meters
 - **IN Only** to display depth measurements in inches
 - **FT Only** to display depth measurements in feet
 - **FT/IN Units** to display depth measurements in feet and inches

Cold Screen / Normal Screen

The **Cold/Normal Screen** menu option allows you to change the screen to have either a **Cold** (black) background or a **Normal** (light) background. Adjusting the screen contrast in increments is also possible, and is necessary at times, such as when there are changes in temperature or in brightness.

Tele Option A/B

If you are operating a newer receiver that has the TLT function with an older remote display that does not have the TLT function, then you must set the receiver's menu option to display **Tele Option B**:

1. Select **Configure** from the main menu screen, and click the trigger.
2. Toggle to the right several times to select **Tele Option A**, and click the trigger. **Tele Option B** will now display (meaning you are set to Tele Option A mode), and your receiver will now communicate with the older remote display.

If you are operating an older receiver that does not have the TLT function with a newer remote display that has the TLT function, then you must change the remote display's setting to show **Tele Option B**.

1. From the remote display's main menu screen, select **Configure** and press the execute button.
2. Press the right arrow several times to select **Tele Option A** and press the execute button. **Tele Option B** will now display (meaning you are set to Tele Option A mode), and this newer remote display will receive signals from the older receiver.

Locator DL / No Locator DL (Enabling and Disabling DataLog Menus)

If you are using the DataLog Mapping System, then you will need to enable the DataLog menu options so that you can access DataLog functions from the Eclipse receiver's main menu screen. With the DataLog menus enabled, you will automatically begin storing data if you push the toggle up when in locate mode. See the *DataLog Mapping System Operator's Manual* provided with your DataLog system or available at www.digitrak.com for more information.

To enable the DataLog menu options:

1. Select **Configure**, and click the trigger.
2. Toggle right several times to select **Locator DL**, and click the trigger. Your receiver will now display the **DataLog** menu options under the Eclipse main menu.

To disable the DataLog menu options, select **No Locator DL** from the **Configure** menu options.

Set Roll / Unset Roll (Enabling and Disabling Roll Offset Function)

The **Set Roll** menu option enables the roll offset function, which is used when the drill bit (tool) and housing are two separate pieces and their roll positions do not match when the tool is torqued-up to the housing. The roll offset function is an electronic compensation to match the transmitter's 12 o'clock position to the tool's 12 o'clock position.

Enabling Roll Offset Function

To enable the roll offset function on the receiver:

1. Power up the receiver.
2. Toggle right to **Configure**, and click the trigger.
3. Toggle right several times to **Set Roll**, and click the trigger (note that this menu item will change to **Unset Roll**).

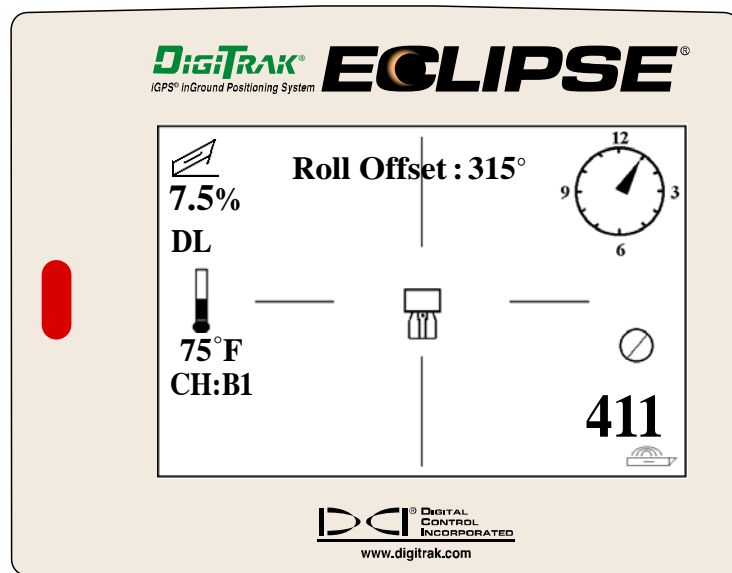
The receiver is now ready for you to use the roll offset function.

Setting Roll Offset Number

To set the roll offset number:

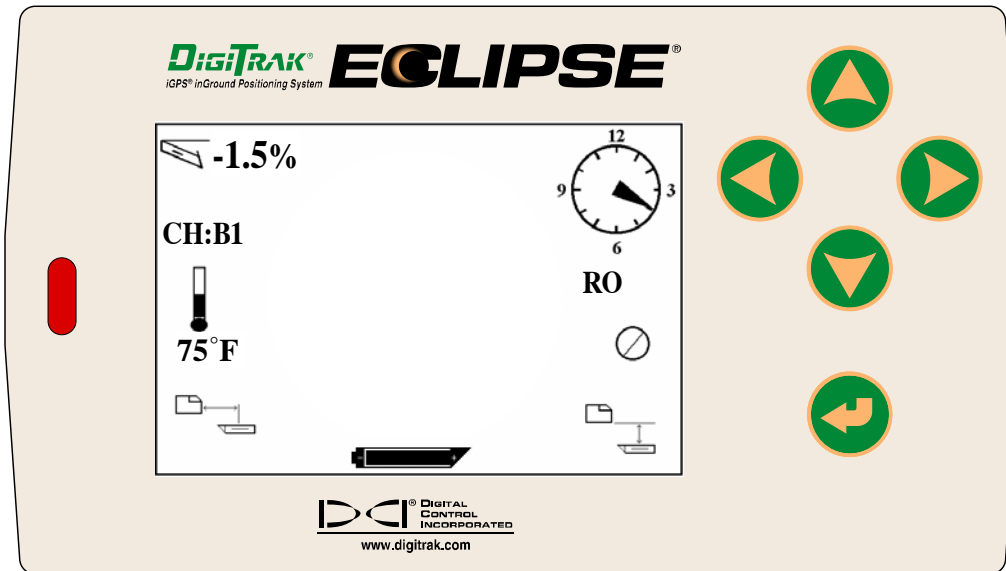
1. Torque-up the tool to the housing.
2. Orient the tool to 12 o'clock.
3. Power up the receiver and the transmitter.
4. Place the transmitter inside the housing.
5. From the receiver's main menu screen, select **Locate** and click the trigger.
6. Toggle right one time, select **Y** for yes, and click the trigger. The transmitter's roll position should now match the tool's position, which is 12 o'clock.

The "Roll Offset" number will appear at the top of the receiver's screen. This number is displayed to indicate that a compensation for the transmitter's roll position has occurred. This number will remain in memory until you change it; therefore, you can calibrate, change the telemetry channel, and replace the battery without affecting this roll offset number.



Eclipse Receiver with Roll Offset Displayed

When the remote display is in remote mode (receiving data from the receiver), you will see the letters “RO” for roll offset underneath the clock, indicating that a compensation for the transmitter’s roll position has occurred.



Eclipse Remote Display with Roll Offset Displayed

Removing Roll Offset Number

If you want to change the roll offset, you must first remove the “old” roll offset number. The instructions to remove the roll offset number are below:

1. Power up the receiver and transmitter.
2. From the receiver’s main menu screen, select **Locate** and click the trigger.
3. Toggle left one time, select **Y** for yes, and click the trigger.

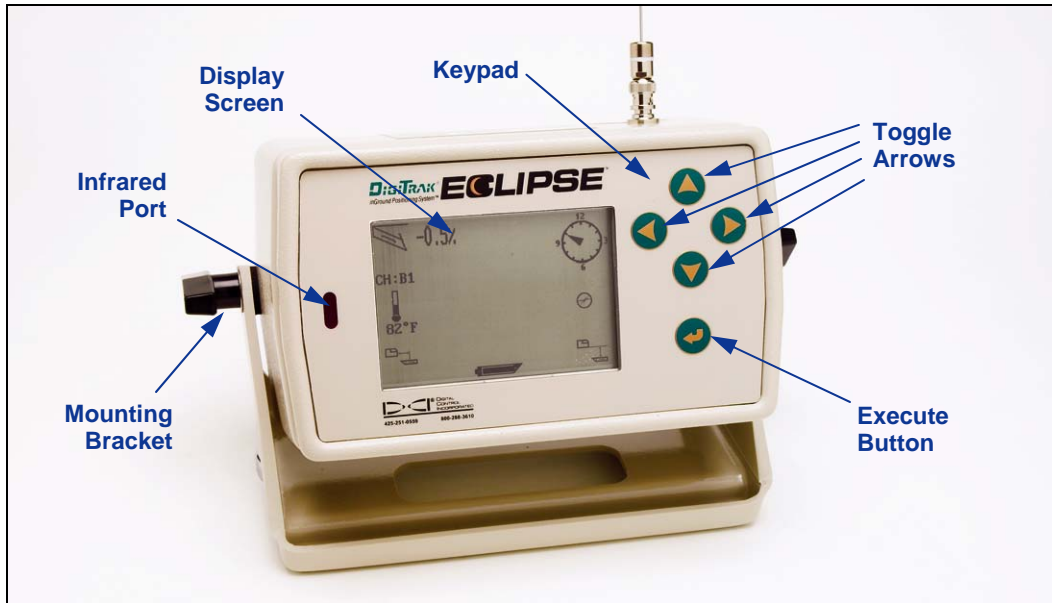
Disabling the Set Roll Menu Option

If you are using a fixed housing that does not require the roll offset function, you should disable the **Set Roll** option so that you do not accidentally change the roll by toggling right while in locate mode. To disable the **Set Roll** option:

1. Power up the receiver
2. Toggle right to **Configure** and click the trigger
3. Toggle right several times to **Unset Roll** and click the trigger

Note that the menu option will change from **Unset Roll** to **Set Roll**.

Remote Display



Eclipse Remote Display

Keypad

On the right side of the display is the keypad used to operate the remote. The four toggle arrow buttons serve the same purpose as the toggle on the receiver, and the execute (curved arrow) button is the same as the trigger on the receiver.

Power On

The Eclipse remote display can be powered using either a DCI NiCad battery pack or an Eclipse DC adapter (ELP). To power the remote display using a NiCad battery, place the battery pack into the back of the remote so that the two exposed terminals make contact with the bottom two springs in the battery compartment

To power the remote display using an ELP, place the ELP into the back of the remote so that the three metal terminals make contact with the three springs in the remote display. Then plug the DC connector into the drill rig's cigarette lighter.



Installing Battery in Remote Display



ELP – Eclipse DC Adapter

When the battery or the ELP is properly installed, you can turn on the Eclipse remote display by pushing the execute button on the keypad. It will take several seconds for the display to appear.

Speaker and Audible Tones

The remote display has a speaker on the back below the battery compartment. The speaker emits warning tones if the transmitter's temperature is increasing to indicate that appropriate and immediate attention is required.

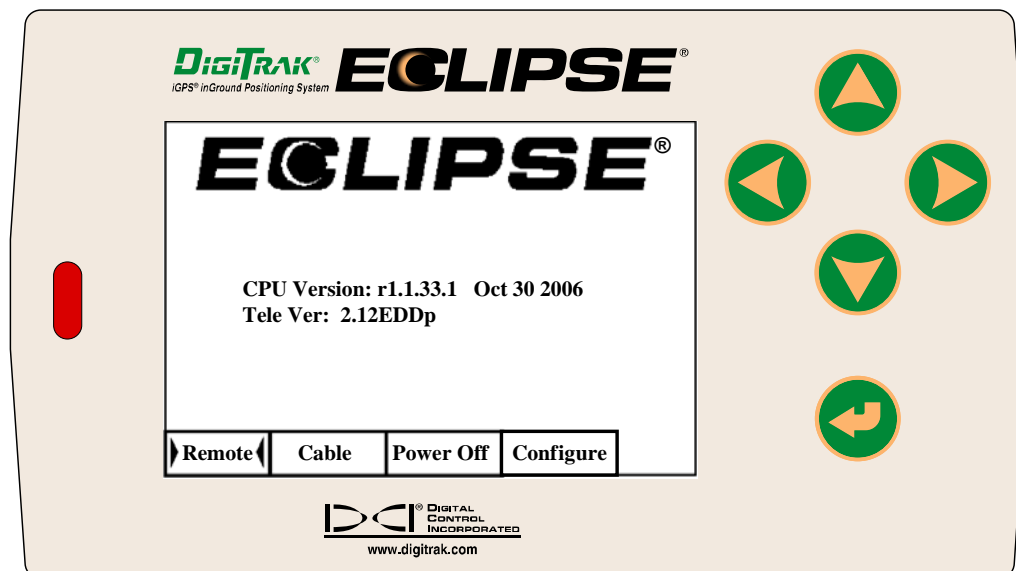
Adjusting Screen Contrast

There are two techniques for adjusting the display screen contrast to gradually lighten or darken it. The remote display must be in remote (or receiving) mode for either technique.

- Hold in the execute button while pushing the right toggle arrow several times to lighten the contrast or the left toggle arrow to darken the display's contrast.
- Push and hold the right toggle arrow to lighten the contrast or the left toggle arrow to darken the contrast while pushing the execute button for the desired contrast.

Main Menu

When the Eclipse remote display is turned on, the main menu screen appears showing the CPU version and the main menu options (see figure below). The main menu options are **Remote**, **Cable**, **Power Off**, and **Configure**.



Remote Display Main Menu

To access one of the main menu options, select the item and then press the execute button once. The result for each menu item is shown in the following table. From any menu screen, you can press the down toggle arrow twice to return to the **Remote** menu.

Remote Display Main Menu Options

Remote	Puts the remote display unit into receiving mode.
Cable	Puts the remote display unit into cable system receiving mode. This mode is required when using the Eclipse cable transmitter. For complete information about operating the Eclipse cable system, see the <i>Cable System</i> section.
Power Off	Turns off the Eclipse remote display. NOTE: If using the Eclipse cable system, the remote must be turned off before making a wire connection (see <i>Cable System</i> section).
Configure	Presents another set of menu options. See the “Configure Menu” section below for an explanation of the Configure menu options.

Configure Menu

The **Configure** menu options for the remote display are similar to those for the receiver, and many operate in the same way. The table below lists the remote display **Configure** menu options in the order that they appear and explains their functions and uses.

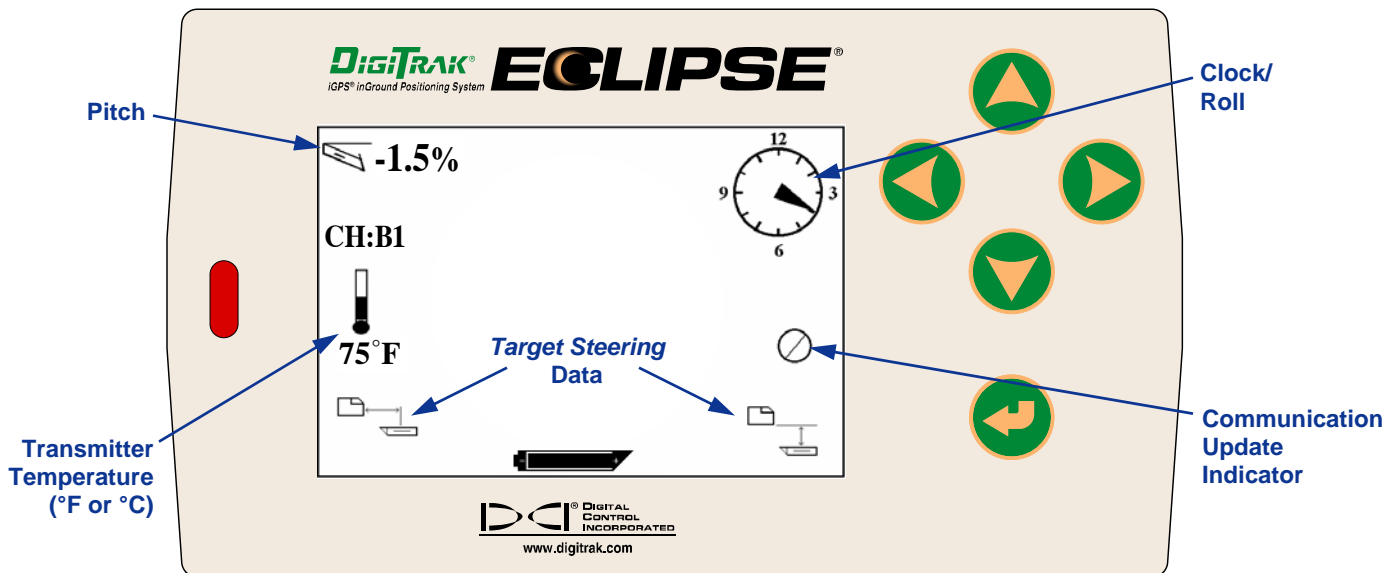
Remote Display Configure Menu Options

Tele Ch.	Changes the telemetry channel setting for the remote display to receive communication from the receiver (see “Changing the Telemetry Channel” in the <i>Receiver</i> section of this manual). NOTE: The remote display must be set to the same channel as the receiver.
° Grade / % Grade	Changes how the transmitter’s pitch information is displayed at the remote display (see “Changing the Grade Mode” in the <i>Receiver</i> section). The pitch can be displayed in percent slope (%) or in degrees (°).
Use Metric / Use English	Changes the depth measurement mode (see “Changing the Depth Measurement Mode” in the <i>Receiver</i> section). The depth can be displayed in metric units or in three forms of English units (IN Only , FT Only , or FT/IN Units). When measuring depth in metric units, the transmitter temperature is displayed in °C; when measuring in English units, the transmitter temperature is displayed in °F.
IN Only / FT Only / FT/IN Units	Changes the English units for the depth setting. Selecting IN Only will display the depth in inches and change the menu option to show FT Only . Selecting FT Only will display the depth in feet and will change the menu option to show FT/IN Units . Selecting FT/IN Units will display depth in feet and inches and will change the menu option to show IN Only . All these depth measurement options display the temperature in °F.
Cold Screen / Normal Screen	Changes from one contrast mode to the other—the screen can have a black (cold) background or a light (normal) background (see “Cold/Normal Screen” in the <i>Receiver</i> section).

Tele Option A/B	Allows the remote display to receive information when its corresponding receiver unit has a different telemetry system, such as when one unit has TLT and the other does not (see “Changing the Telemetry Channel” and “Tele Option A/B” in the <i>Receiver</i> section)
Locator DL / No Locator DL	Enables the DataLog Mapping System menu options so that you can access DataLog functions from the Eclipse receiver’s main menu screen and store data when locating (see “Locator DL / No Locator DL” in <i>Receiver</i> section).
Set Roll / Unset Roll	Enables the roll offset function, which allows the transmitter’s roll position to be compensated to match the tool’s roll position (see “Set Roll / Unset Roll” in <i>Receiver</i> section). This function on the remote display is only used with an Eclipse cable transmitter or the Eclipse SST transmitter. You do not need to enable this function unless you are using one of these transmitters (see <i>Cable System</i> section). When you are using a battery-operated transmitter, the roll offset is enabled at the receiver. The receiver then sends the correct roll information to the remote, and the letters “RO” for roll offset are displayed underneath the roll clock.
Code	This menu option is provided for DCI to use for calibration during manufacturing and for diagnosing problems for repairs.
Exit	Returns display to the main menu screen.

Remote Display Screen

During normal drilling use, the **Remote** menu option must be selected so that the remote display screen (shown below) is visible. The remote screen displays the drilling parameters for the drill rig operator’s use, including transmitter pitch and roll, transmitter temperature, and *Target Steering* data. The *Target Steering* data will only be shown when the *Target Steering* function is being used. The communication update indicator rotates to show that data are being received from the receiver.



Remote Display Screen
(when receiver is not above FLP, RLP, or LL)

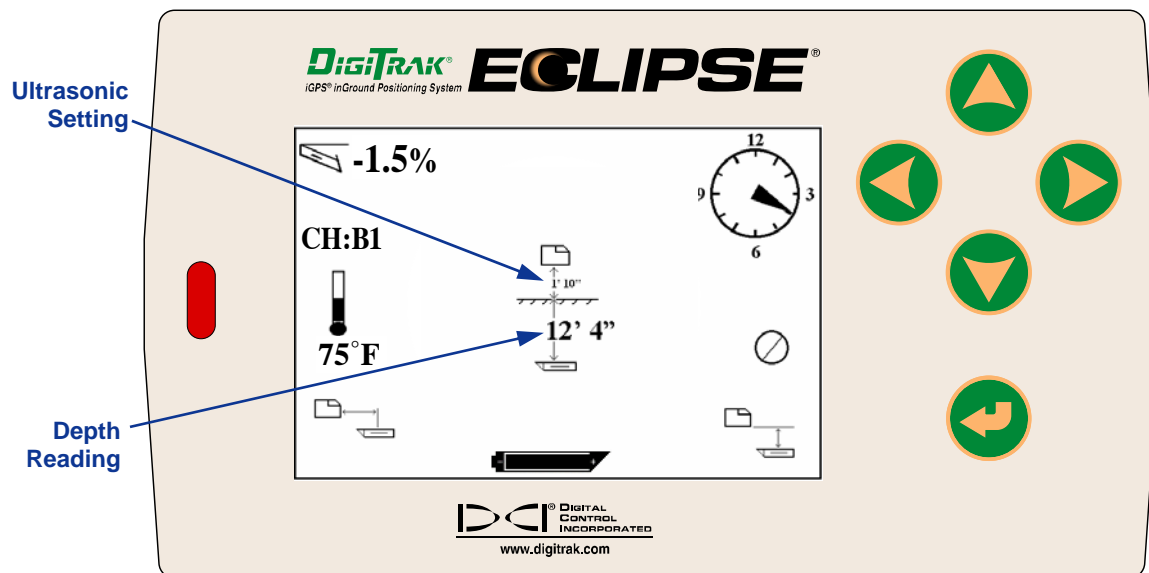
NOTE: The receiver must be in locate mode to send signals to the remote display.

The depth or predicted depth of the transmitter can also be viewed on the remote display. The receiver must be positioned over either the locate line (LL) or one of the locate points (FLP or RLP) for this function to work—see “Locate Points (FLP & RLP) and Locate Line (LL)” in the *Locating* section. Also, this function is only available on Eclipse systems produced after February 2002.

NOTE: The capability to view the depth and predicted depth screens on the remote display is a function that was added in February 2002. Older systems did not have this function. If you have an older system and would like to upgrade, contact DCI.

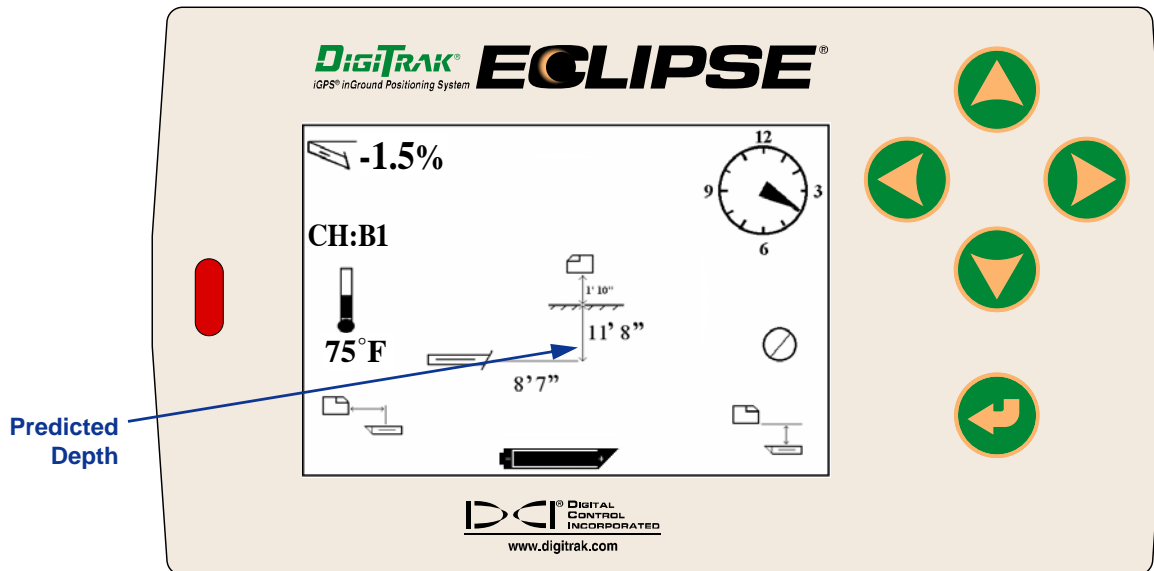
Once the receiver is positioned over the LL, FLP, or RLP, the receiver operator holds in the trigger to take the depth or predicted depth reading. The remote display will emit a single tone to notify the operator that the depth information is being displayed. This depth/predicted depth information will remain on the remote display's screen for 10 seconds or as long as the receiver's trigger is held in.

To view a depth reading on the remote display, the receiver must be above the transmitter or the LL while the trigger is held in.



**Depth Screen on Remote Display
(when receiver is above LL)**

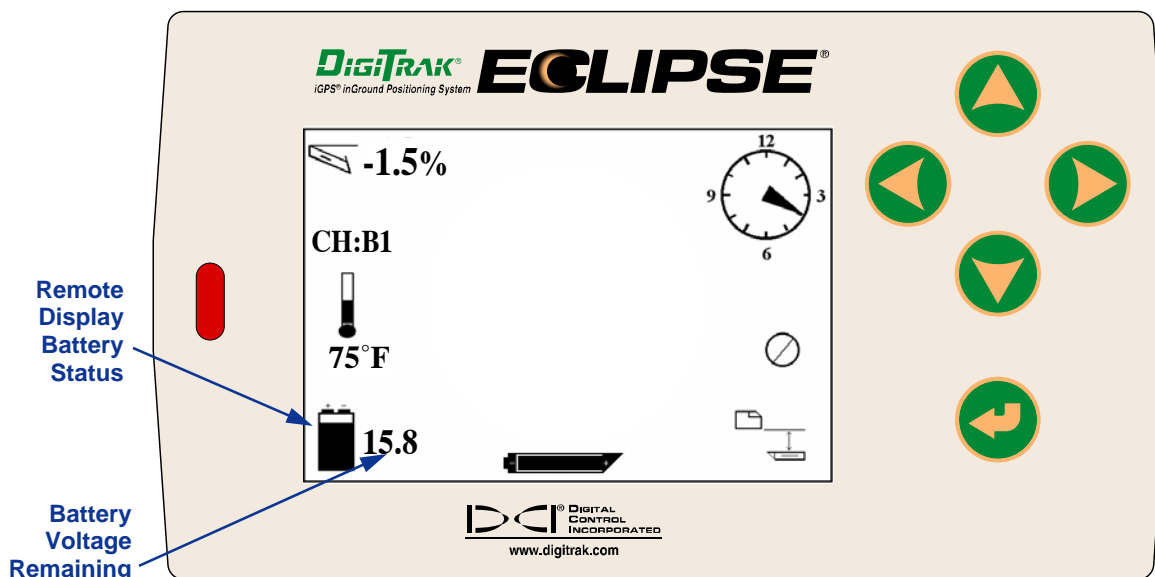
To view the predicted depth on the remote display, the receiver must be above the FLP or RLP while the trigger is held in. The predicted depth will only be valid if the receiver is over the FLP; data will appear if the receiver is over the RLP, but the data will be invalid.



**Predicted Depth Screen on Remote Display
(when receiver is above FLP or RLP)**

If the receiver is not positioned directly above the locate line or a locate point and the trigger is held in, then the depth or predicted depth will not be displayed on either the receiver or the remote display. The receiver must be positioned above the locate line or a locate point in order to get a depth or predicted depth reading.

To view the remote display's NiCad battery status, push the execute button. An icon of the battery will appear in the lower left corner with the corresponding voltage remaining. A solid black battery indicates a full charge. When the battery icon displays half full (remaining voltage will be between 14.2 and 14.8), you should shut off the remote display and install a fully charged battery.



Remote Display Battery Status

Transmitter

Types of Eclipse Transmitters

DCI manufactures four different battery-operated Eclipse transmitters—a standard transmitter (black tube), a short-range mini transmitter (gray tube), a long-range transmitter (light-gray tube), and a dual-frequency transmitter (lavender tube). We also offer a cable transmitter (see *Cable System* section for information on the cable transmitter). For especially difficult locating jobs, such as when walkover locating is not possible, DCI offers the SST wireline transmitter, which is part of the Eclipse SST advanced HDD guidance system. For deep auger-boring applications, we offer a 60-in. (1524-mm) auger-boring cable transmitter that can be tracked for line and precision grade down to 200 ft (61 m). Call DCI or visit www.digitrak.com for more information on these products.

The standard Eclipse transmitter emits a 12-kHz signal and provides a depth range of approximately 50 ft (15.2 m). The standard transmitter is 15.00 in. (381.0 mm) long and 1.25 in. (31.8 mm) in diameter.



Standard Eclipse Transmitter

The short-range mini transmitter emits a 12-kHz signal and provides a depth range of approximately 15 ft (4.6 m). The mini transmitter is 8.00 in. (203.2 mm) long and 1.00 in. (25.4 mm) in diameter. DCI offers an adapter for the mini transmitter to fit in a standard-sized housing. The outer dimensions of the adapter with the mini transmitter inside are exactly the same as those of the standard and dual-frequency transmitters (15.00 in. x 1.25 in. [381.0 mm x 31.8 mm]). Call DCI for additional information.



Mini Eclipse Transmitter



Mini Eclipse Transmitter with Housing Adapter



Long-Range Eclipse Transmitter

The long-range Eclipse transmitter emits a 12-kHz signal and provides a depth range of approximately 85 ft (25.9 m). The long-range transmitter is 19.00 in. (482.6 mm) long and 1.25 in. (31.8 mm) in diameter. This transmitter requires the use of one 3.6-V DCI SuperCell Lithium Battery. The use of two C-cell alkaline batteries will result in very short battery life—approximately 2 hours. Therefore, DCI recommends that you only use the SuperCell Lithium Battery in the long-range transmitter.



Eclipse Dual-Frequency Transmitter

The dual-frequency transmitter is the same size as the standard transmitter, and it can be set to transmit in dual-frequency mode (sending signal at both 1.5-kHz and 12-kHz frequencies) or in single-frequency mode (sending signal at 12 kHz). Each frequency mode offers specific advantages:

- The dual-frequency mode provides a depth range of approximately 40 ft (12.2 m) at either frequency, and is recommended in areas where rebar, wire mesh, or other metal (passive) interference may be encountered.
- The single-frequency mode (12 kHz) provides a depth range of approximately 60 ft (18.3 m) and is intended for use in areas of active interference.

When using the standard Eclipse transmitter (black tube), the mini transmitter (gray tube), the long-range transmitter (light-gray tube), or the dual-frequency transmitter set to single-high (SH) or dual-high (DH) mode, you should see **Low Fre** on the receiver's main menu display (meaning you are operating at high frequency). When using the dual-frequency transmitter set to dual-low (DL) mode, you should see **High Fre** on the receiver's main menu display (meaning you are operating at low frequency).

Pitch and Roll Information

Eclipse transmitters measure pitch in percent slope or degree increments. Pitch measurements are displayed in 0.1% increments from 0% to $\pm 100\%$ (or 0° to $\pm 45^\circ$).

The transmitter roll is displayed in 24 positions, similar to the hour and $\frac{1}{2}$ hour positions on a clock.

Batteries

The 15.00-in. (381.0-mm) transmitters require two C-cell alkaline batteries or one DCI SuperCell Lithium Battery. The 19.00-in. (482.6-mm) long-range transmitter requires one DCI SuperCell Lithium Battery, although two C-cell alkaline batteries will work for a very short period of time. The mini transmitter requires one AA alkaline battery. DCI does not recommend using non-alkaline or rechargeable batteries. The batteries are loaded into the battery compartment with the positive terminals going in first.

The amount of power remaining in the batteries is displayed on the depth and predicted depth display screens (see *Locating* section). However, the SuperCell battery will display as fully charged until moments before it goes dead. Therefore, it is necessary to monitor drilling hours when using the SuperCell.

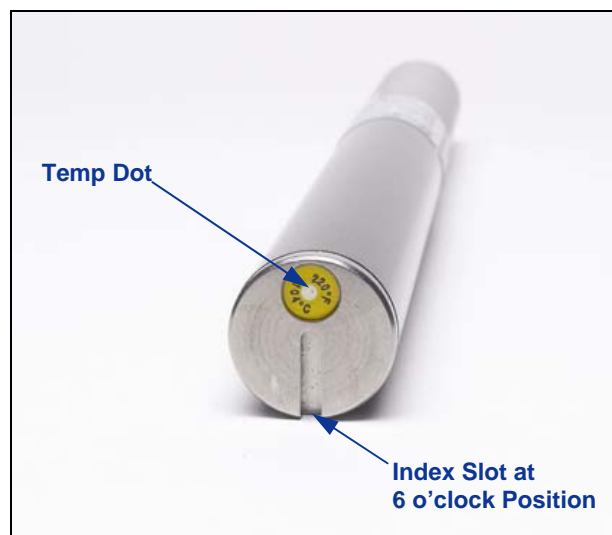
When using two C-cell alkaline batteries, it may be beneficial to solder or wrap the batteries to avoid battery chatter in hard ground conditions.

Temperature Updates and Overheat Indicator

Transmitter temperature information is displayed both digitally and graphically on the receiver. When the transmitter's temperature increases, audible warning tones are emitted by both the receiver and the remote display. Temperatures are displayed in degrees Fahrenheit (°F) when the depth measurement mode is in English units, and degrees Celsius (°C) when the depth mode is in metric units.

Normal drilling temperatures range from 64°F (16°C) to 104°F (40°C). DCI recommends that you keep the transmitter temperature below 104°F (40°C) by slowing penetration rates and/or adding more drilling fluid.

Each transmitter has a temperature overheat indicator (temp dot) located on the stainless-steel front end cap. The temp dot on a new transmitter is white (see photo). If the temp dot is black, the transmitter has been exposed to temperatures in excess of 220°F (104°C). The transmitter should then be deemed unreliable and should not be used on further projects.



Front End Cap of Transmitter Showing Temp Dot and Index Slot

Start Up and Frequency Modes

Starting the Standard Eclipse Transmitter

1. Remove battery cap, and load two C-cell alkaline batteries (or a SuperCell lithium battery) into the battery compartment, positive terminal(s) first.
2. Replace the battery cap and screw it in until it is flush with the end of the battery compartment.
3. To view the transmitter information, select **Locate** from the main menu screen on the receiver, and click the trigger.
4. Verify that the signal strength is approximately 528 by placing the receiver 10 ft (3 m) from the transmitter (in the housing). You will see **SH** above the temperature thermometer to indicate the transmitter is in single-high mode. (The standard transmitter only has one frequency.)

Starting the Mini Eclipse Transmitter

1. Remove battery cap, and load one AA-cell alkaline battery into the battery compartment, positive terminal first.
2. Replace the battery cap and screw it in until it is flush with the end of the battery compartment.
3. To view the transmitter information, select **Locate** from the main menu screen on the receiver, and click the trigger.
4. Verify that the signal strength is 360 to 370 by placing the receiver 10 ft (3 m) from the transmitter (in the housing). You will see **SH** above the temperature thermometer to indicate the transmitter is in single-high mode. (The mini transmitter only has one frequency.)

Starting the Long-Range Eclipse Transmitter

1. Remove battery cap, and load one SuperCell lithium battery into the battery compartment, positive terminal first.
2. Replace the battery cap and screw it in until it is flush with the end of the battery compartment.
3. To view the transmitter information, select **Locate** from the main menu screen on the receiver, and click the trigger.
4. Verify that the signal strength is approximately 620 by placing the receiver 10 ft (3 m) from the transmitter (in the housing). You will see **SH** above the temperature thermometer to indicate the transmitter is in single-high mode. (The long-range transmitter only has one frequency.)

Starting the Eclipse Dual-Frequency Transmitter

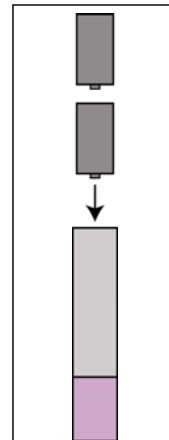
The Eclipse dual-frequency transmitter can be set to transmit in two different modes—dual-frequency mode (transmitting at 1.5 kHz and 12 kHz) or single-frequency mode (transmitting at 12 kHz).

The frequency mode can only be changed at startup when the batteries are loaded. You cannot change the frequency mode of the transmitter while drilling.

The frequency mode is established by the orientation of the transmitter at startup, when the batteries are loaded into the battery compartment.

Starting the Dual-Frequency Transmitter in Dual-Frequency Mode

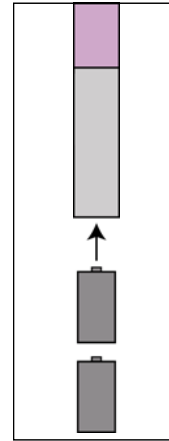
1. Remove the battery cap, and hold the transmitter vertically with the battery compartment up and the front end pointing down (see diagram).
2. Load two C-cells (or a SuperCell lithium battery) into the battery compartment with the positive terminal entering first.
3. Replace the battery cap while rotating the transmitter in this vertical position until the cap is flush with the end of the battery compartment.
4. Power up the receiver, and verify that the main menu option shows **Low Fre** on the main menu screen.
5. Select **Locate** from the receiver's main menu screen, and click the trigger.
6. You will see **DH** above the thermometer on the left side of the screen to indicate the transmitter is in dual-high mode.
7. Verify that the signal strength is 530 to 540 by placing the receiver 10 ft (3 m) from the transmitter (in the housing), and record the value.
8. Return to the main menu screen on the receiver, select **Low Fre**, and click the trigger.
9. Select **Locate** from the main screen, and click the trigger.
10. You will see **DL** above the thermometer on the left side of the screen to indicate the transmitter is in dual-low mode.
11. Verify that the signal strength is 480 to 490 when the receiver is 10 ft (3 m) from the transmitter (in the housing), and record the value.



Loading Batteries for Dual Mode

Starting the Dual-Frequency Transmitter in Single-Frequency Mode

1. Remove the battery cap, and hold the transmitter vertically with the battery compartment down and the front end pointing up (see diagram).
2. Load two C-cells (or a SuperCell battery) into the battery compartment with the positive terminal(s) entering first.
3. Replace the battery cap while rotating the transmitter in this vertical position until the cap is flush with the end of the battery compartment.
4. Power up the receiver and verify that you see **Low Fre** on the main menu screen.
5. Select **Locate** from the receiver's main menu screen, and click the trigger.
6. You will see **SH** above the thermometer on the left side of the screen to indicate the transmitter is in single-high mode.
7. Verify that the signal strength is approximately 565 when the receiver is 10 ft (3 m) from the transmitter (in the housing), and record the value.



Loading Batteries for Single Mode

Sleep Mode (Automatic Shutoff)

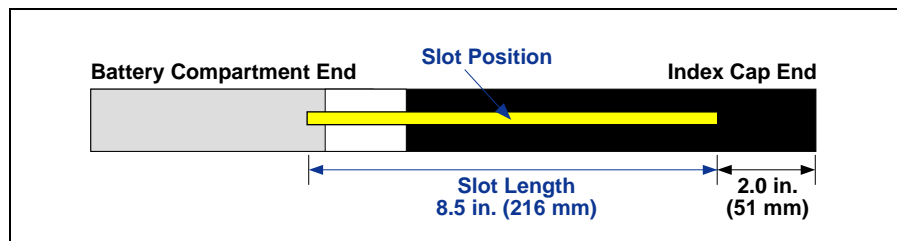
The Eclipse transmitter will shut down (go into "sleep" mode) to conserve battery power if it is stationary for 15 minutes. To "wake up" the transmitter, simply rotate the drill string.

Transmitter Housing Requirements

To achieve maximum range and battery life for all of DCI's transmitters, the slots in the housing must be long enough and correctly positioned. Slot measurements should always be taken from the inside of the housing.

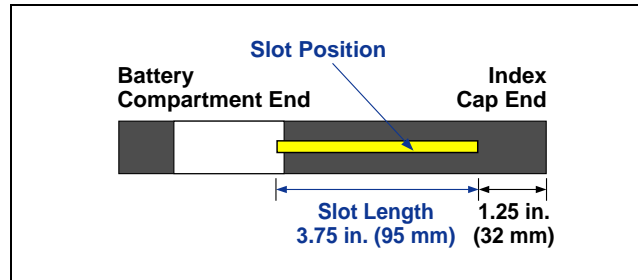
DCI recommends at least three slots equally spaced around the circumference of the housing. The slots must be at least 1/16 or 0.0625 in. (1.6 mm) wide. The position and length requirements of the housing slots for the different Eclipse transmitters are given below.

For the standard and dual-frequency transmitters (15.00 in./381.0 mm long), each slot should begin at least 2.0 in. (51 mm) from the front or index cap end of the transmitter and must be at least 8.5 in. (216 mm) long (see figure below).



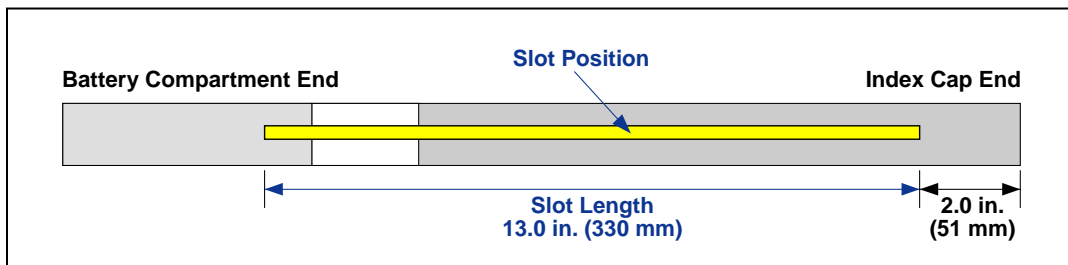
Standard and Dual-Frequency Transmitter Housing Slot Requirements

For the mini transmitter (8.00 in./203.2 mm long), each slot should begin at least 1.25 in. (32 mm) from the front or index cap end of the transmitter and must be at least 3.75 in. (95 mm) long (see figure below).



Mini Transmitter Housing Slot Requirements

For the long-range transmitter (19.00 in./482.6 mm long), each slot should begin at least 2.0 in. (51 mm) from the front or index cap end of the transmitter and must be at least 13.0 in. (330 mm) long (see figure below).



Long-Range Transmitter Housing Slot Requirements

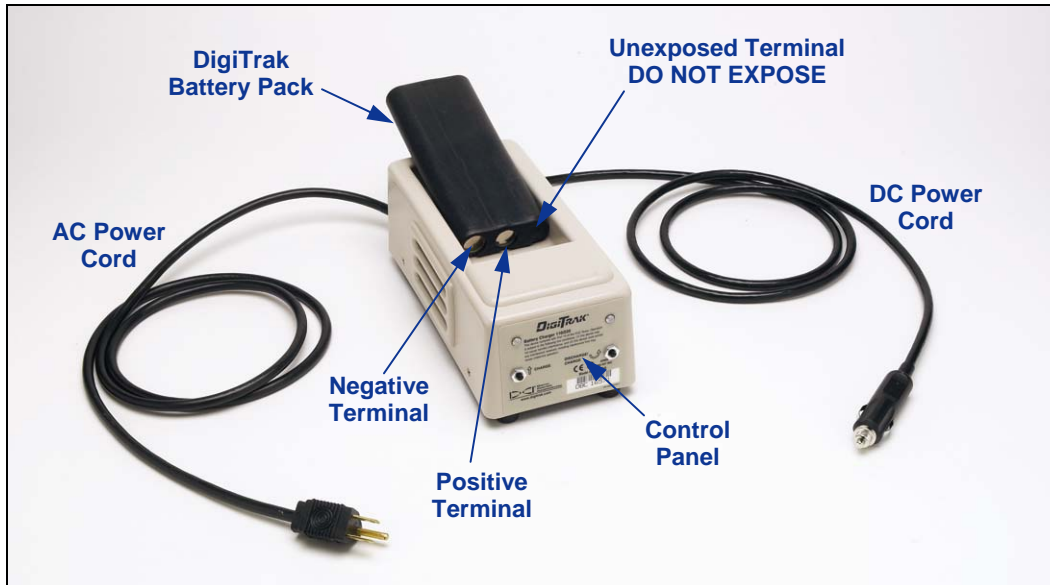
General Transmitter Care Instructions

- Clean the springs in the battery compartment and the threads of the battery cap and O-ring. Emery cloth can also be used to remove any oxidation buildup.
- Verify that the transmitter fits snugly into the housing. It may be necessary to wrap the transmitter with tape or O-rings.
- Send in the Product Registration card for the 90-day limited warranty.



Notes

Battery Charger



Battery Charger

Both the Eclipse receiver and the remote display use a DCI rechargeable NiCad battery pack that is provided with the system together with a DCI battery charger. The battery pack should be fully discharged before recharging; this is known as conditioning the battery. A fully discharged battery measures 14.4 V DC or shows low battery status on the receiver or remote display.

The battery charger can be powered from an AC or DC power source and is equipped with a conditioning or discharge cycle designed to remove the “memory effect” from the battery. The charger will operate from any AC voltage (wall outlet) between 100 V and 240 V without modification (you may need to convert the plug). This allows the same battery charger to be used in many different countries. The battery charger is also equipped with an automotive cigarette lighter adapter for 12 V to 28 V DC charging.

The voltage on a fully charged battery is between 16.5 V DC and 17.1 V DC. A battery is considered discharged at 14.4 V DC.

A fully charged DCI NiCad battery pack should power the Eclipse receiver for approximately 4 hours. A fully charged NiCad battery pack should power the remote display for approximately 4 hours.

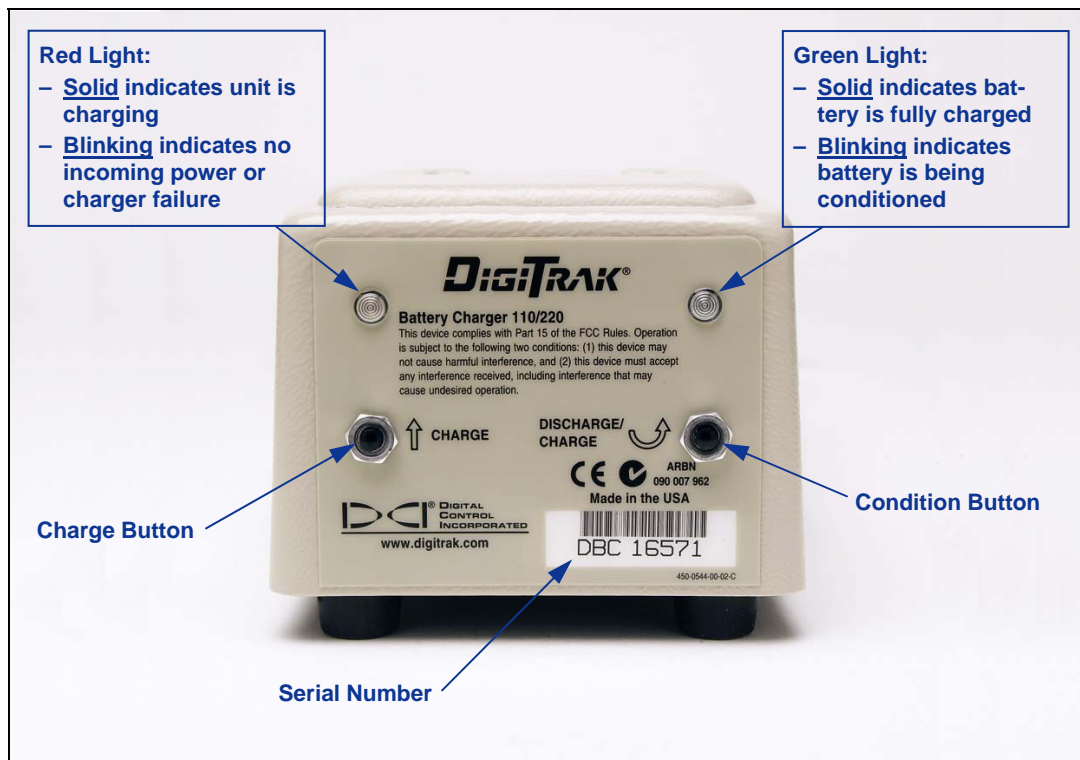
Only two terminals are exposed on the NiCad battery pack. There is a third terminal under the black insulating material. If the third terminal accidentally becomes exposed, do not try to charge the battery pack or you may damage the battery charger. Such a battery may cause fire or can damage the remote display or receiver.

The battery charger is grounded by the safety ground pin of the AC line power plug.

No standard off-the-shelf battery will physically fit in the battery charger, and no nonrechargeable batteries are provided in that physical format.

NOTE: Only charge DCI NiCad batteries in the battery charger. Charging or using other types of batteries may damage the charger, the receiver, or the remote display and will void the warranty.

To charge a battery, place the battery into the charger with the terminal end making contact with the springs. The red light on the left will illuminate, indicating that the unit is charging (see figure below).



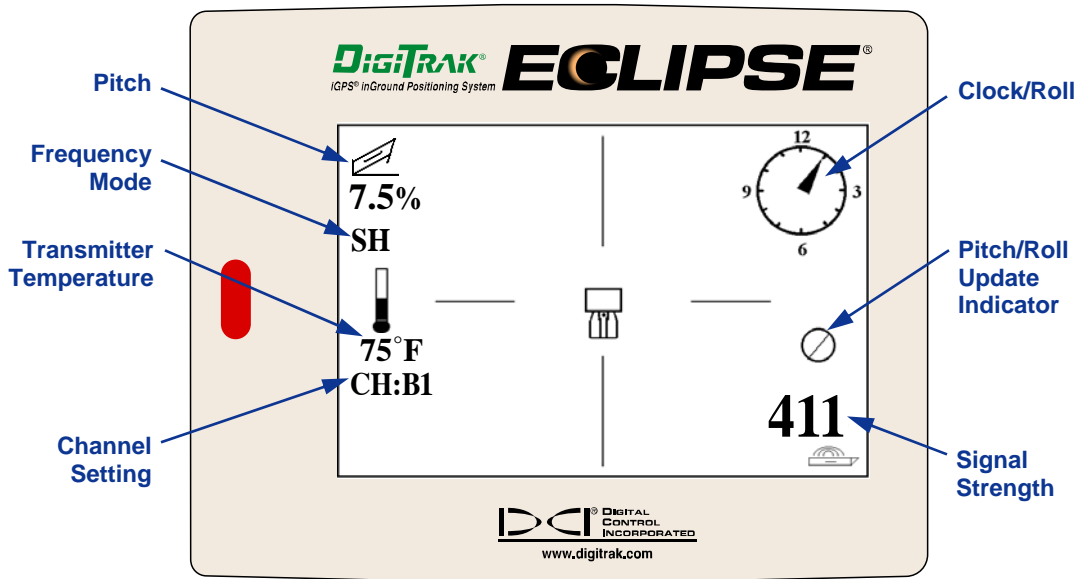
Battery Charger Control Panel

The battery will take between 20 minutes and 2 hours to charge. When the charging cycle has been completed, the green light on the right will illuminate.

NOTE: If a battery is left in the charger during a power interruption, the red or green light may flash and the battery will begin to discharge on its own. After the power has resumed, simply remove and replace the battery pack and press the desired charge or discharge (condition) button.

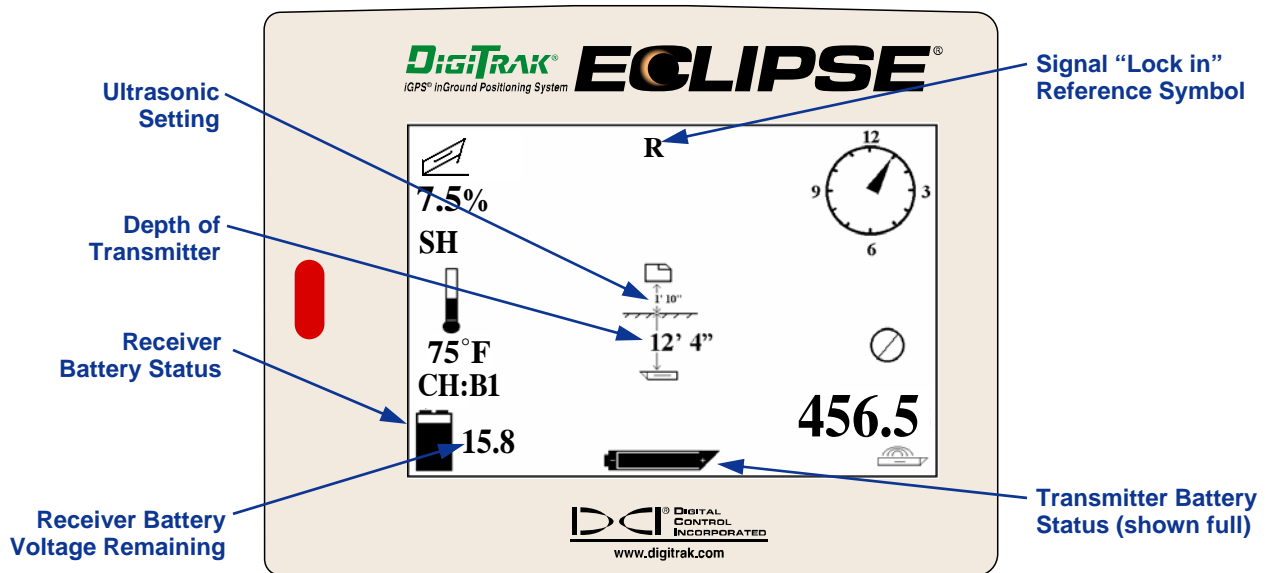
Locating

The graphic display on the Eclipse receiver uses icons to show readings and system status information. The locate mode screen provides real-time data about the transmitter's temperature, frequency mode, pitch, roll, and signal strength, in addition to displaying the channel setting.



Locate Mode Screen

The depth mode screen (trigger held in) provides the same real-time data given on the locate mode screen and also displays the ultrasonic height setting, the transmitter's depth, and battery status information for both the receiver and the transmitter. The "lock in" symbol (the letter "R") appears when you hold in the trigger to "lock in" on the reference signal at a locate point.



Depth Display Screen

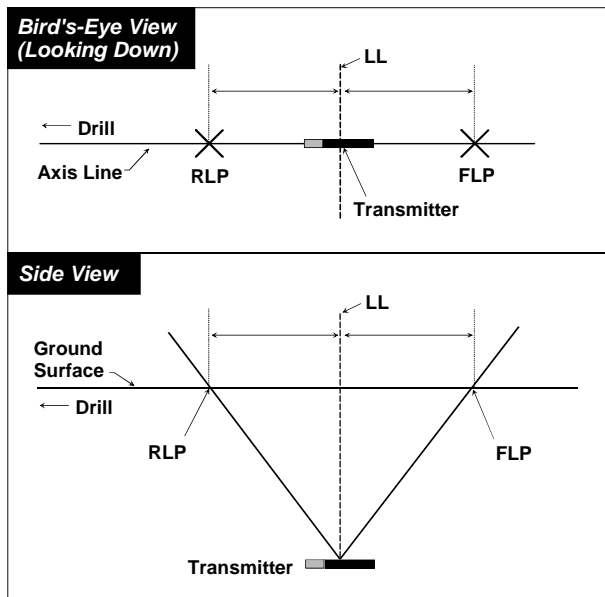
Locate Points (FLP & RLP) and Locate Line (LL)

Three positions or locations within the transmitter's field are used to locate the transmitter below ground. Two of these locations represent extensions of the transmitter. One point is in front of the transmitter (the front locate point or FLP), and the other is behind the transmitter (the rear locate point or RLP).

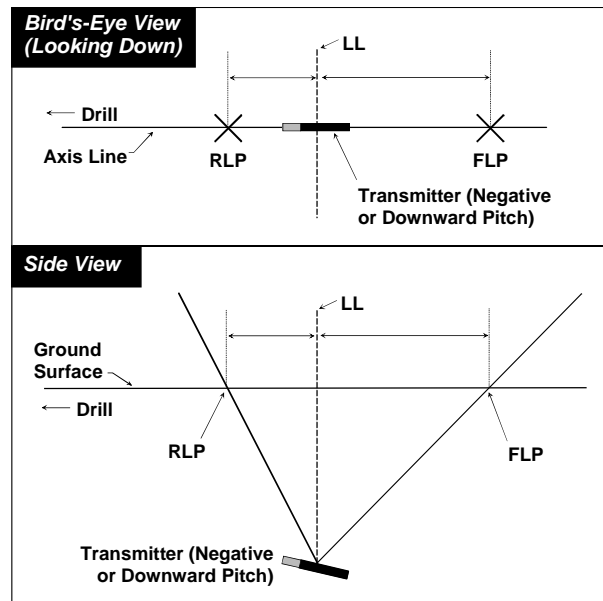
The third location is a line that represents the position of the transmitter. This line is perpendicular to the transmitter and is referred to as the locate line or LL.

The figure on the left below shows the geometry of the FLP, RLP, and LL from top (bird's-eye) and side views. Note how the RLP and FLP are equal distances from the LL when the transmitter is level and the ground surface is level.

The figure on the right shows the geometry of the locate points and locate line when the transmitter is at a negative or downward pitch. Note how, in this case, the RLP and FLP are at different distances from the LL.



Top and Side Views of FLP, RLP, and LL When Transmitter Is Level with the Ground

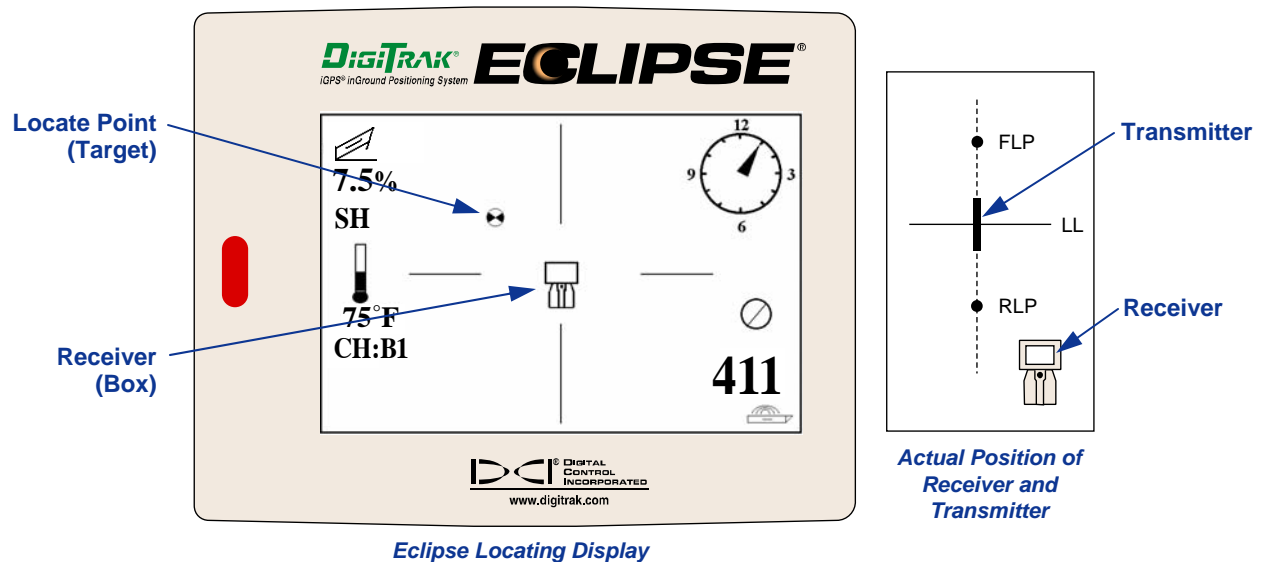


Top and Side Views of FLP, RLP, and LL When Transmitter Is at Negative or Downward Pitch

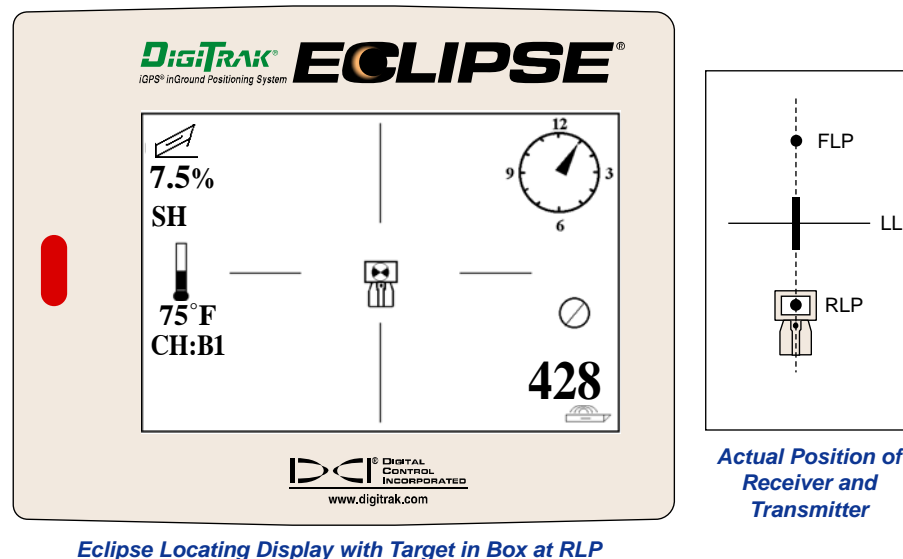
Locating Procedure

The Eclipse system can be used to locate the transmitter while facing either toward the drill or away from the drill. The locating procedure given here assumes you are facing away from the drill with the transmitter out ahead of you.

1. Begin locating by clicking the trigger after you have selected the **Locate** option from the main menu screen. The locating display will appear, as shown in the graphic on the left below. The Eclipse locating display (on the left) shows the position of the locate point (the target) with respect to the receiver (the box in the center of the display). The graphic on the right shows the actual position of the receiver, the transmitter, and the locate points. Note that the RLP is ahead of and to the left of the receiver, as shown in the Eclipse display by the target symbol.

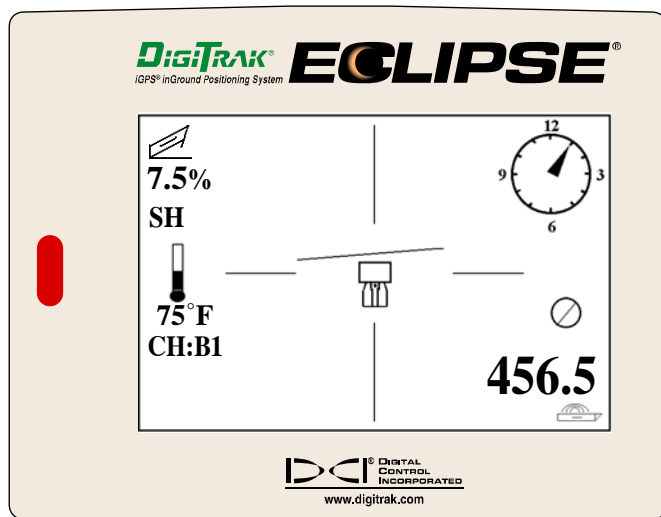


2. Position the receiver until you get the target in the box as shown below. You are now standing with the receiver positioned over the RLP.

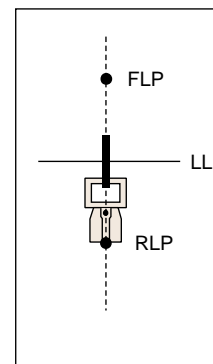


NOTE: To ensure you are over the RLP, you can rotate the receiver 360°, being careful to keep the receiver display at the center of the rotation. The target should stay in the same position in the box on the receiver's display. If it does not, then the receiver's antenna may be malfunctioning—you should contact DCI Customer Service, 800-288-3610 or 425-251-0559, for assistance.

3. Hold in the trigger for at least one second to “lock in” on the reference signal (you will see the “R” symbol appear at the top of the display until you release the trigger).
4. Continue walking away from the drill and toward the transmitter. You will see the target move from the box to the bottom of the screen, and then it will quickly appear at the top of the screen. You will then see the LL appear as pictured below.

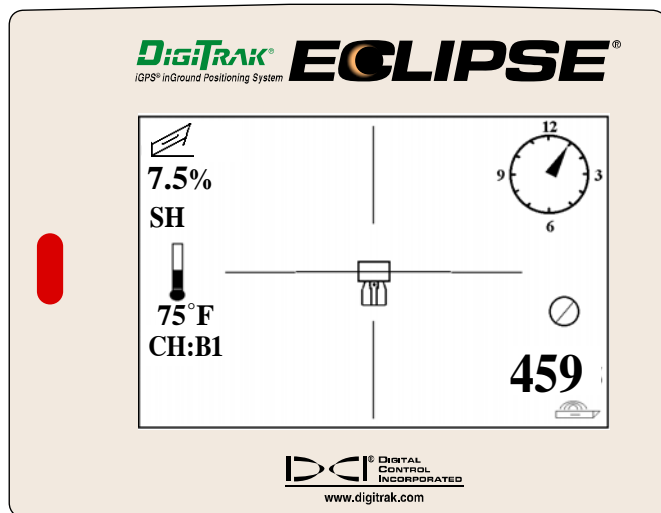


Eclipse Locating Display with Operator Approaching LL

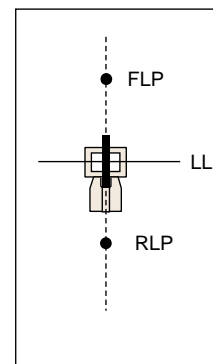


Actual Position of Receiver and Transmitter

5. Position the receiver until the LL lines up with the two horizontal cross hairs. You are now standing on the LL. To determine the exact lateral position of the transmitter, you will need to find the FLP.

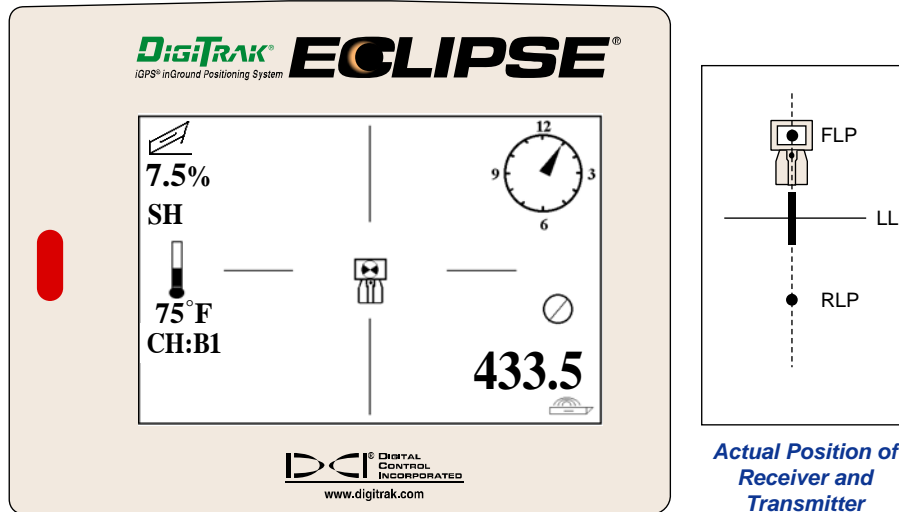


Eclipse Locating Display with Operator at LL



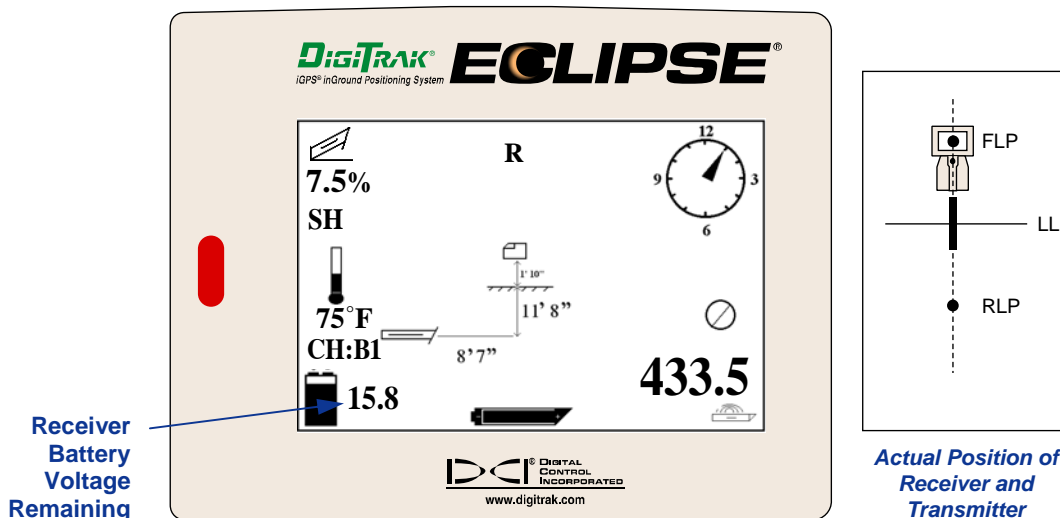
Actual Position of Receiver and Transmitter

- Continue to walk out ahead of the transmitter and position the receiver until the target is in the box as shown below.



Eclipse Locating Display with Target in Box at FLP

- While at the FLP, hold the trigger in to observe the predicted depth (11 ft 8 in. in the figure below), which is the depth the transmitter will be at when it passes under the FLP, and the horizontal distance in front of the transmitter (8 ft 7 in.), which is the distance that the transmitter will travel to reach the predicted depth. You will also see the ultrasonic setting (1 ft 10 in.) below the receiver icon and the receiver's battery status, including the amount of voltage remaining, in the bottom left corner.

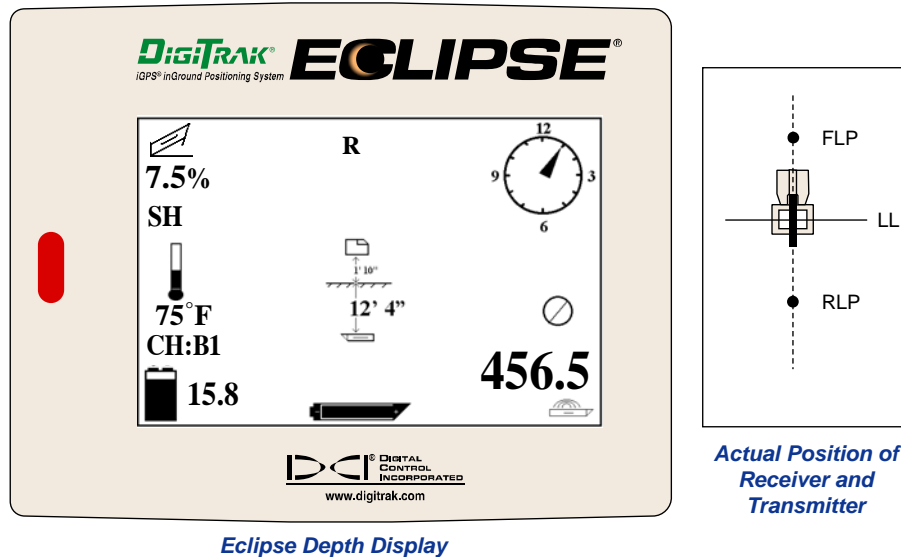


Eclipse Predicted Depth Display

When the battery icon appears half full (remaining voltage will be between 14.2 and 14.8), you should shut off the receiver and replace the battery with a fully charged battery.

NOTE: You should replace the receiver battery when the receiver battery icon appears half full (remaining voltage between 14.2 and 14.8).

8. While standing on the FLP and facing back toward the drill, it is possible to “sight in” or align the FLP with the RLP. This axis line is at a 90° angle (perpendicular) to the LL. Where this axis line crosses the LL is where the transmitter will be found, below ground.
9. Position the receiver at the intersection of the LL and the line between the RLP and FLP—you will be above the transmitter. From this location you can observe the depth of the transmitter by simply holding in the trigger. You will also see the ultrasonic setting and, in the bottom left corner, the receiver’s NiCad battery status.



If you choose to locate the transmitter by standing out in front of it and facing the drill, you can use the same technique as described above. However, you will first find the FLP, then the LL, and finally the RLP. Remember that you must “lock in” on the reference signal at the FLP (instead of the RLP) if you use the method of locating from the front, facing the drill.

It is not always necessary to find both of the locate points (RLP and FLP). However, for the most accurate locating, DCI recommends that you find both the FLP and the RLP. The line connecting the FLP to the RLP will provide you with the heading of the transmitter (tool) as well as its position below ground. The heading information can be particularly useful when the transmitter (tool) hits something that deflects it to the left or right, resulting in a change of heading.

DCI does not recommend locating the transmitter using the peak signal method.

NOTE: It is very important to position the receiver accurately. The depth reading can be inaccurate if the receiver is not positioned directly over the drill head.

The Target Steering® Function

The *Target Steering*® function allows the Eclipse receiver to be placed out ahead of the drill head and used as a steering target. To activate the *Target Steering* function, you must program the receiver with the desired target depth number. The drill head can then be guided to a point directly below where the receiver has been placed.

The Eclipse system assumes level topography for the most accurate *Target Steering* results. It also assumes that the value programmed for depth is within practical drilling conventions for the bend radius of the drill string and that of the product being installed. In general, the intended drill path from the current transmitter position to the target should be simple and not require large pitch or depth changes. As a rule, the depth cannot change by more than 4 ft (1.2 m) per 35 ft (10.7 m), and the pitch cannot change by more than 14% per 35 ft (10.7 m).

This section presents information on determining a feasible target depth, programming the target depth into the receiver, positioning the receiver, and using the remote display's *Target Steering* screen to steer to the target.

NOTE: DCI does not recommend using the *Target Steering* function in dual-low (DL) mode.

Determining Feasible Target Depth

For the most conservative *Target Steering* operation, we assume that the ideal drill path is a circular arc with a radius that accommodates the bend radius of most drill strings and products being installed. As shown in the diagram below, the feasible steering area is limited to the shaded region bounded by the two circular arcs.

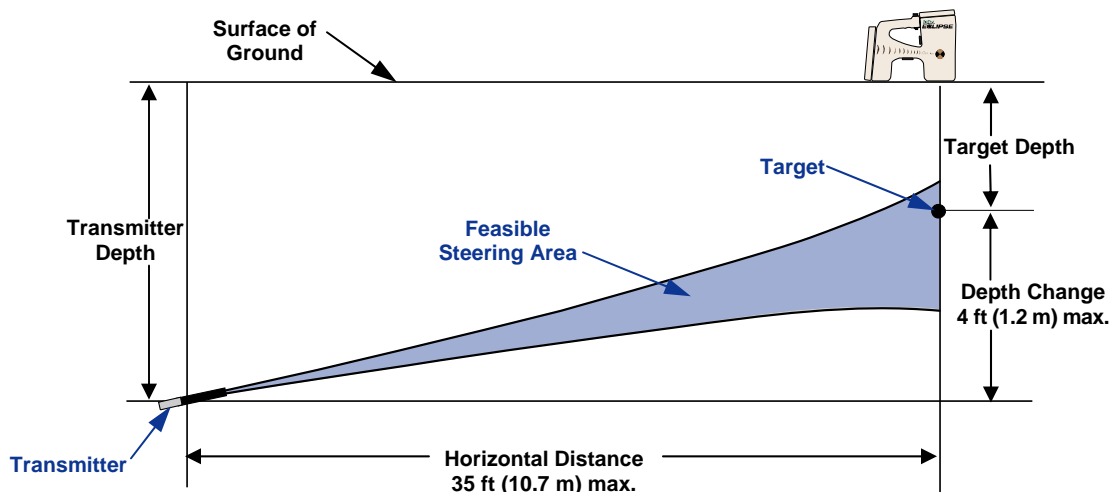


Diagram of Feasible Steering Area

Maximum depth change is approximately 4 ft (1.2 m) over horizontal distance of 35 ft (10.7 m).

The maximum distance that the Eclipse receiver can be placed out ahead of the drill head for Target Steering is 35 ft (10.7 m). Over this 35-ft range, the following parameters apply:

- The maximum depth change is approximately 4 ft (1.2 m).
- The maximum pitch change is approximately 14%.

To determine if your desired target depth is feasible:

1. Use the Eclipse receiver to obtain the current transmitter depth with respect to level ground surface.
2. Subtract the current transmitter depth from your desired target depth to obtain the desired depth change.

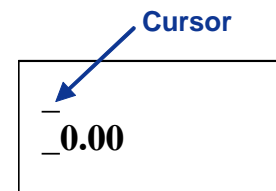
NOTE: If the target depth is above the transmitter, then the target depth number is positive; if it is deeper than the transmitter, then the target depth number is negative.

3. If the desired depth change is less than 4 ft (1.2 m), then you can program the desired target depth as the target depth (see next section, "Programming Target Depth"). However, if the depth change is greater than 4 ft (1.2 m), then the desired target depth is not feasible. You will either have to pull back to increase the available horizontal distance or you must drill toward a different target.

NOTE: DCI does not recommend using the *Target Steering* function in dual-low (DL) mode.

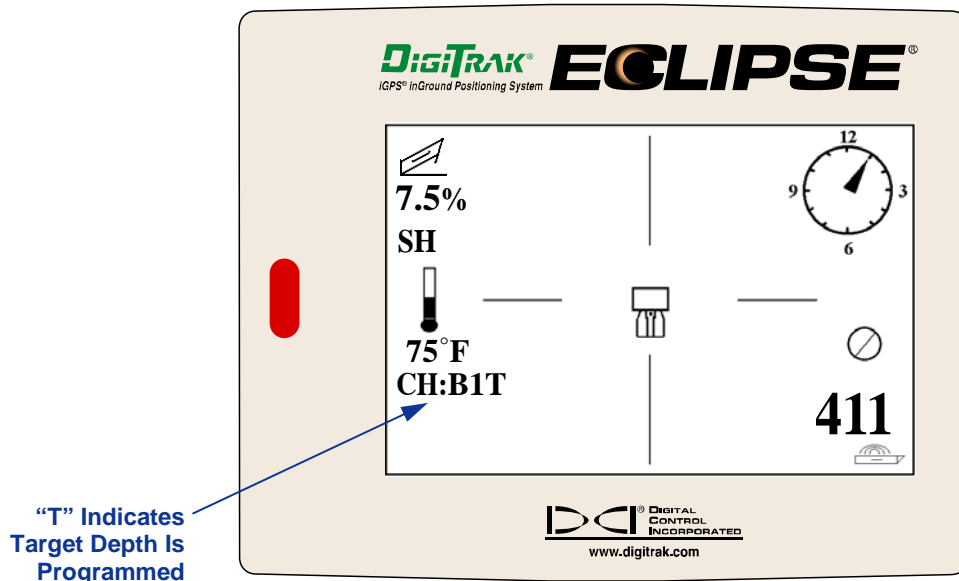
Programming Target Depth

1. Toggle to the **Configure** menu item from the main menu screen on the receiver, and click the trigger.
2. Toggle to the **Target Depth** menu item, and click the trigger. You will see an input area similar to that shown in the figure to the right.
3. Enter the correct target depth number using the toggle. The number must be in decimal format corresponding to either feet or meters. You do not need to enter a negative sign when programming the Eclipse receiver with the target depth number.



NOTE: If you are using **FT/IN Units** for your depth measurement units, you must enter the target depth number in feet in decimal format not in feet and inches. You do not need to change your depth measurement mode.

- When you have entered the correct target depth number, click the trigger. When the target depth is programmed and you are in locate mode, you will see a "T" (for target) next to the channel setting in the lower left corner.



Receiver Screen with Target Depth Programmed

NOTE: If you are not using the target depth mode, you should set the target depth to 0.00.

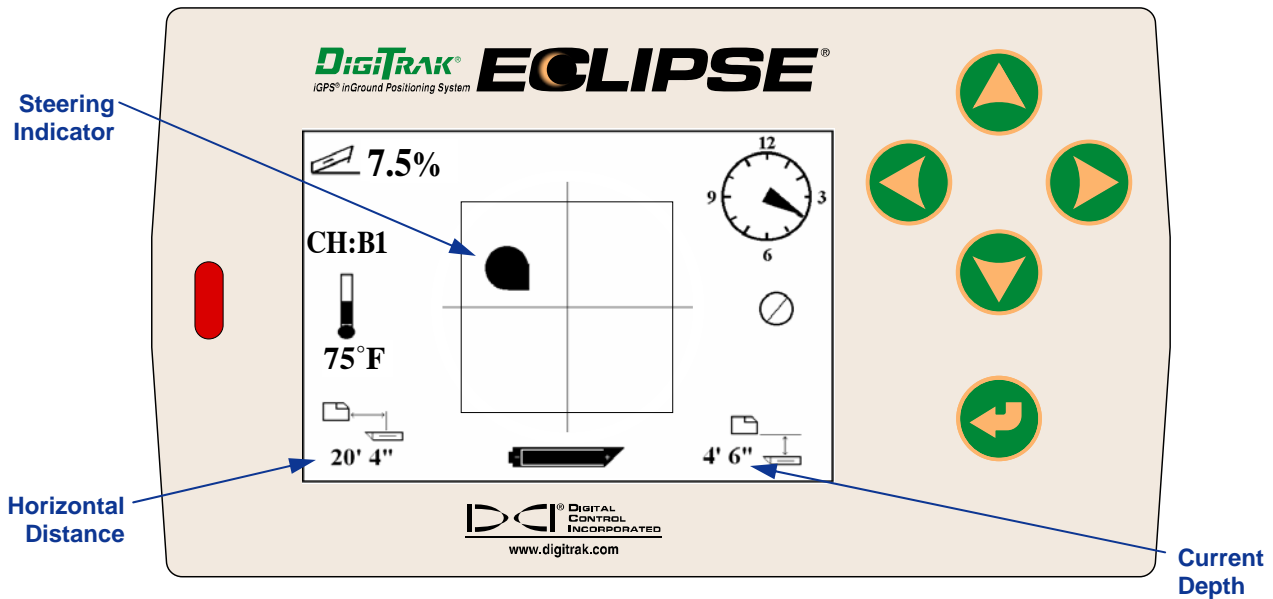
Positioning Receiver as Target

The *Target Steering* procedure requires correct placement of the receiver. The receiver must be placed out in front of the transmitter with its back end (where the NiCad battery pack is inserted) facing the drill. The maximum horizontal distance from the transmitter that the receiver should be placed is approximately 35 ft (10.7 m).

NOTE: It is very important that the horizontal placement of the receiver as well as the value input for the target depth number are within the allowable bend radius of the drill string or the product being installed.

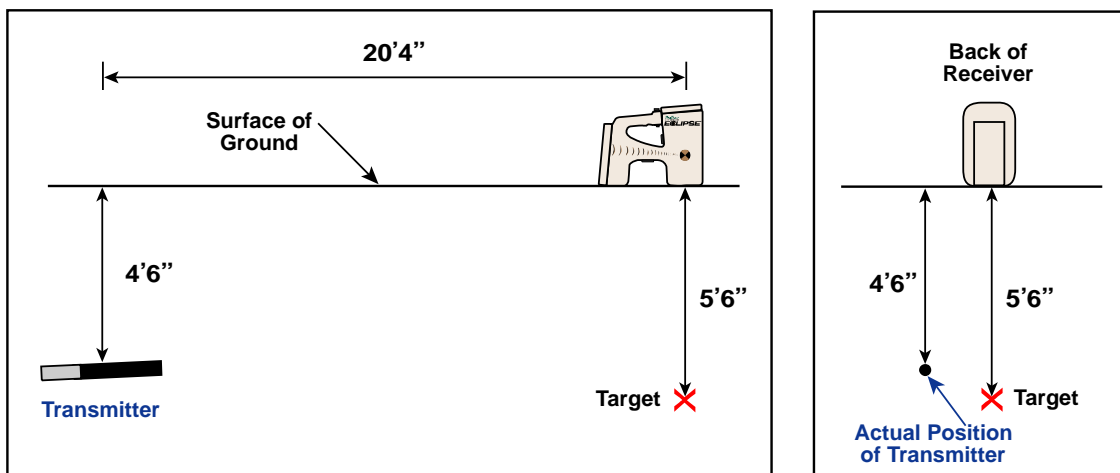
Steering to the Target

Once the target depth number has been entered on the receiver and the receiver is in position as the target, select **Remote** from the main menu screen on the remote display to see the *Target Steering* screen, as shown below. The steering indicator in this case shows that the drill head is to the left and too high for the intended path. The steering indicator should be dead center in the display if you are correctly heading to your programmed target depth. A steering command of 4 o'clock would bring the drill head toward the target. Note that, for quick viewing and interpretation, the pointed end of the steering indicator corresponds to the clock position of the head. The horizontal distance from the drill head to the receiver is indicated at the bottom left part of the display. At the bottom right, the current depth of the drill head is indicated.



Target Steering Screen on Remote Display

A side view of the position of the Eclipse receiver and of the transmitter is shown below on the left. An end view of the same setup is shown on the right.



Side and End Views Showing Positions of Receiver, Transmitter, and Target

Cable System



Eclipse Cable System

The Eclipse cable system is designed specifically for bores that:

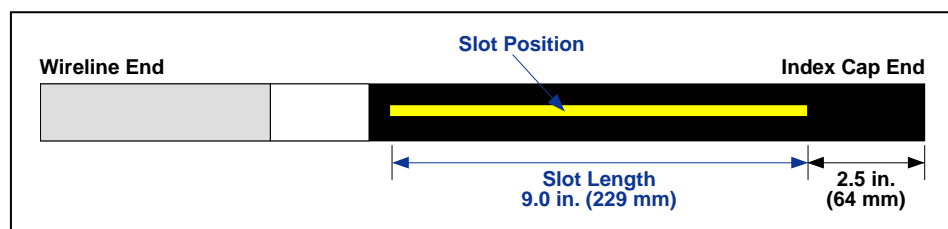
- Have depths in excess of 50 ft (15.2 m).
- Have lengths that require several days to drill.
- Do not allow walkover locating.
- Are in high-interference areas.

The depth and locating ranges of the Eclipse cable system are both approximately 80 ft (24.4 m). These ranges are dependent upon environmental conditions and characteristics of the housing. Depth and lateral location information is tracked using the Eclipse receiver.

Cable System Components

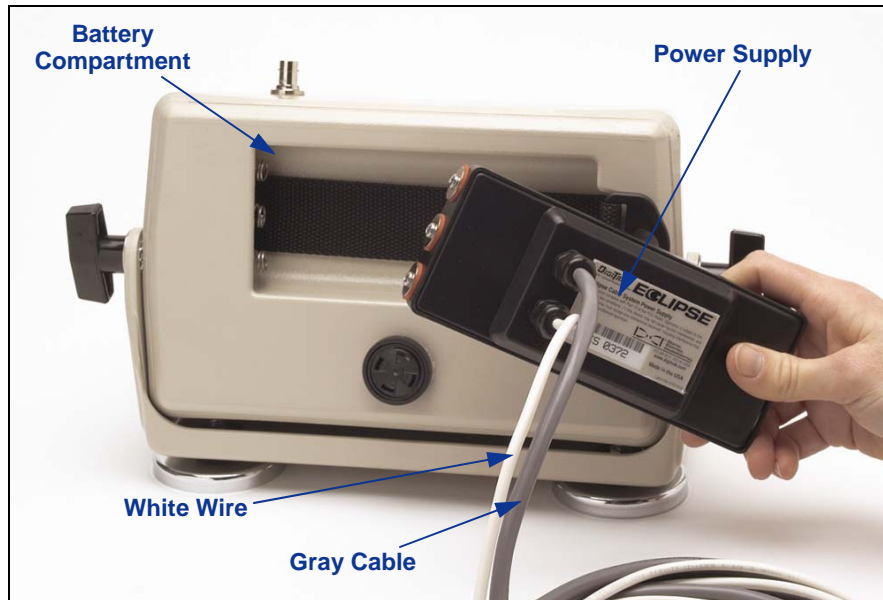
The Eclipse cable system consists of four main components (cable transmitter, power supply, remote display, and cable extraction/insertion tool) and a power source, which are described below.

Eclipse Cable Transmitter – This transmitter measures 19.00 in. (482.6 mm) in length by 1.25 in. (31.8 mm) in diameter. It requires a special rear-load housing with an end plug that allows the transmitter's cable to exit the housing. The end plug requires a compression fitting to seal the transmitter from the drilling fluid. The housing must also have at least three slots equally spaced around the circumference of the transmitter that measure 9.0 in. (229 mm) in length and at least 1/16 or 0.0625 in. (1.6 mm) in width (see figure) for proper signal emission.



Slot Geometry on Cable Transmitters

Power Supply – This unit is inserted into the battery compartment at the back of the remote display. It is hard wired to the Eclipse cable transmitter with a 10-gauge (white) wire and to the power source with a gray cable that contains 14-gauge black and red wires.



Insertion of Power Supply in Remote Display

Remote Display with Cable Function – This specially configured remote display supplies power from the power source to the cable transmitter and displays the cable transmitter's information. All Eclipse remote display units manufactured after February 2002 are equipped with this cable function and will show the **Cable** option in the main menu when the unit is turned on (see *Remote Display* section). Remote displays manufactured prior to February 2002 can be upgraded to the cable function. To upgrade your Eclipse remote display, contact DCI.

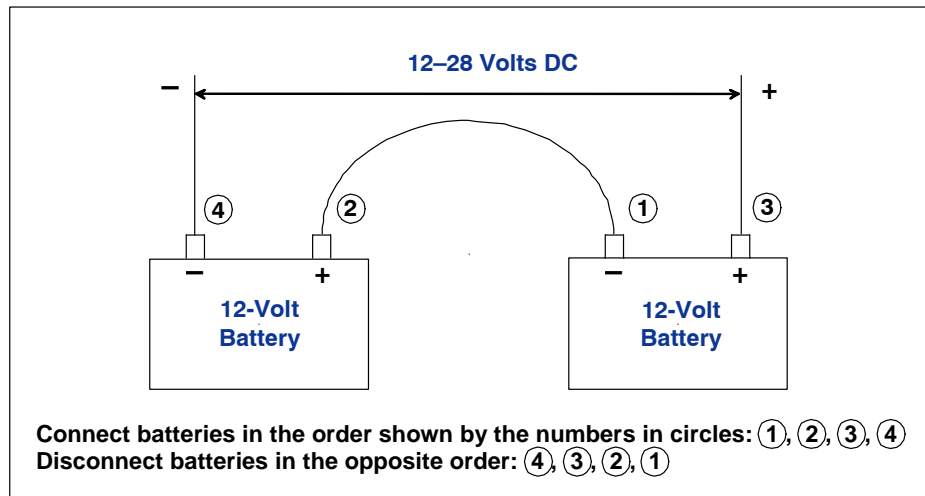
Cable Extraction/Insertion Tool – This tool is used for inserting and extracting the Eclipse cable transmitter to or from the housing. Two threaded holes (1/4"-20 thread) are provided at the back of the cable transmitter for threading the extraction tool (see photo).

NOTE: Never remove the cable transmitter from the housing by pulling on the wire.



Cable Transmitter with Cable Extraction/Insertion Tool Screwed into End

Power Source – Lead-acid automotive batteries that supply between 12 and 28 V DC are used for the power source. For bores shorter than 1000 ft (305 m), one 12-V battery will suffice. If the bore length increases beyond 1000 ft (305 m) or advance rates decrease, additional batteries may be added in series (see diagram).



Adding Batteries in Series

Non-DCI Supplies Required for Operating the Cable System

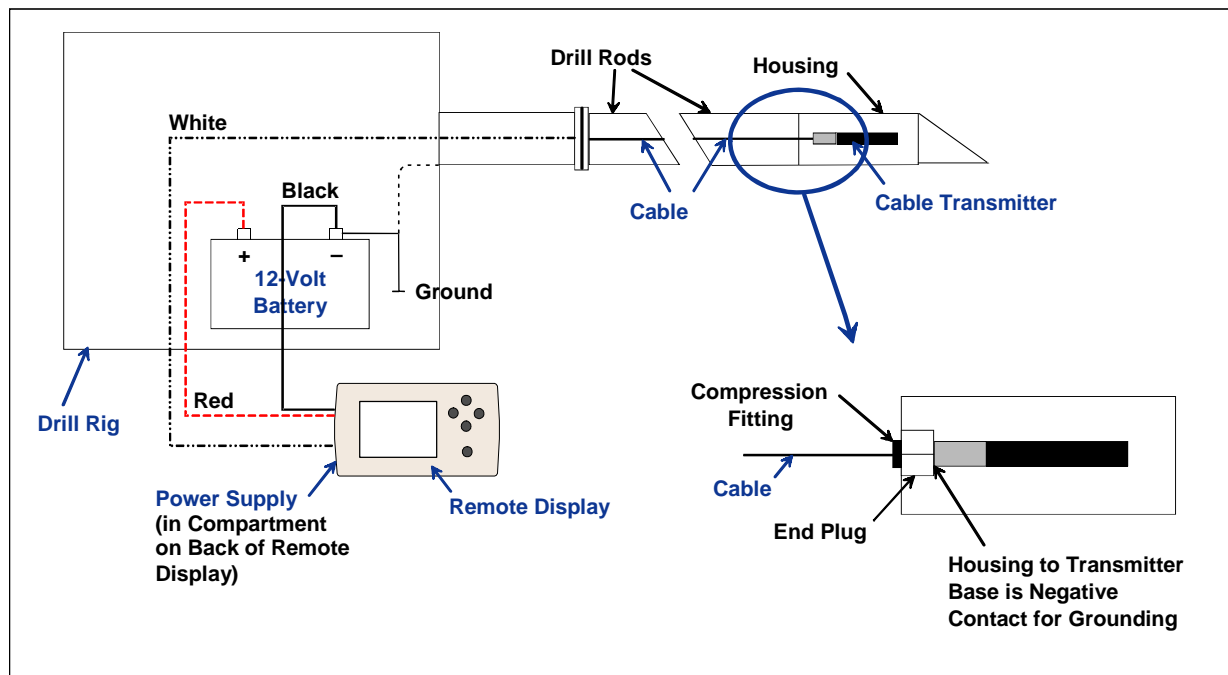
Items such as compression fittings, 10-gauge copper wire, heat shrink, butt splices, and collector ring assemblies are not available from DCI. Drill manufacturers or tooling manufacturers will have information on collector ring (slip-ring) assemblies, mud swivels, and compression fittings. Electrical supply houses will carry the rest of the equipment needed to connect the wires as drill rods are added to the drill string.

A new option available from DCI is a product called the CableLink[®] connection system, which eliminates the need for butt splices and heat shrinks. The CableLink system is permanently installed into the drill pipe, and the wire connection occurs automatically when the pipe ends are threaded together. For more information, contact DCI.

NOTE: A multimeter should be available for power testing/troubleshooting. For detailed instructions on troubleshooting the Eclipse cable system, please contact DCI.

Connecting Power Supply to Power Source and Cable Transmitter

The gray wire that extends from the power supply has two wires within it—a red wire and a black wire. The black wire is the ground; it connects to the negative battery terminal, and the red wire connects to the positive battery terminal. The white wire connects to the cable transmitter wire (see diagram). The Eclipse remote display and power supply must be connected directly to the power source, not through a wiring harness or the drill's auxiliary panel.



Connecting Cable System Components

Grounding the Cable Transmitter

The cable transmitter must be grounded or it will not work—no signal or data will be sent to the remote display. The ground point on the cable transmitter is the metal end cap (where the wire extends). When the cable transmitter is properly fitted into the housing, the ground connection will occur automatically, because it is grounded through the drill. When testing the cable transmitter outside of the housing, you can make a ground connection by taking a piece of wire and touching the negative terminal of the battery with one end and touching the other end of the wire to the metal end cap of the cable transmitter.

Cable Transmitter On/Off

Before you can power up the remote display, you must ensure that the power supply, power source, and cable transmitter are properly connected, as discussed in the previous sections. After properly connecting the cable system, push the execute button to power up the remote display. Then select the **Cable** menu option. This will enable the remote display to send power to the cable transmitter.

To turn the power off, press the toggle arrows on the remote display to select the **Power Off** option and press the execute button. DCI recommends that you turn off the power to the cable transmitter prior to working with the wire, such as when adding a new drill rod.

At the end of the drilling day it is necessary to stop power to the cable transmitter to conserve the battery life of the power source. Use the **Power Off** menu option to turn off the power, then disconnect the power source from the remote display.

Calibrating the Cable Transmitter

The cable transmitter is calibrated using the 1-point calibration procedure at a distance of 10 ft (3 m)—for the proper procedure, refer to the 1-Point Calibration discussion under the “Configure Menu” in the *Receiver* section. DCI recommends that you always check the depth readings at various locations against a tape measure to confirm good calibration.

Enabling the Roll Offset Function on the Remote Display

The roll offset function is used when the drill bit (tool) and housing are two separate pieces and their roll positions do not match when the tool is torqued-up to the housing. The roll offset function is an electronic compensation to match the transmitter’s 12 o’clock position to the tool’s 12 o’clock position.

Enabling Roll Offset Function

To enable the roll offset function on the remote display:

1. Power up the remote display.
2. Select **Configure** from the remote display’s main menu and press the execute button.
3. Press the right arrow several times to select **Set Roll**, and press the execute button; this menu option will change to **Unset Roll**.

The remote is now ready for you to set the roll offset number, which you should do if the transmitter’s 12 o’clock position does not match the tool’s 12 o’clock position.

Setting Roll Offset Number

To set the roll offset number:

1. Torque-up the tool to the housing.
2. Orient the tool to 12 o’clock.
3. Place the cable transmitter into the housing and power up using the Eclipse power supply.
4. From the main menu on the remote display, select **Cable** and press the execute button.

5. Press the right arrow, and press it again to select **Y** for yes, then press the execute button.

Note the “RO” or roll offset number that appears at the top of the remote display to indicate that a compensation for the transmitter’s roll position has occurred. This number will remain in memory until you change it; therefore, you can calibrate, change the telemetry channel, and replace the battery without affecting this roll offset number.

If you will be tracking the cable transmitter with the receiver, you will also need to set the roll offset on the receiver to ensure that both units display the same roll information. If you have not already enabled the roll offset function on the receiver using the **Set Roll** menu option, refer to “Set Roll / Unset Roll (Enabling and Disabling the Roll Offset Function)” in the *Receiver* section.

To set the roll offset number on the receiver, after enabling the roll offset function:

1. Torque-up the tool to the housing.
2. Orient the tool to 12 o’clock.
3. Place the cable transmitter into the housing and power up using the Eclipse power supply.
4. From the remote display’s main menu, select **Cable** and press the execute button.
5. From the receiver’s main menu screen, select **Locate** and click the trigger.
6. Toggle up one time, select **Y** for yes, and click the trigger. The transmitter’s roll position should now match the tool’s position, which is 12 o’clock.

The receiver will display the roll offset number at the top of the screen and the remote display will show the roll offset number at the top as “RO”.

Locating Using the Cable System

Locating using the cable transmitter system is identical to locating using the battery-operated Eclipse transmitter—see the *Locating* section.

The receiver and remote display must be set to the same channel (see the “Configure Menu” section in the *Receiver* and *Remote Display* sections for instructions on changing the telemetry channel settings and the Telemetry Options or TLT functions). The receiver and remote will display the pitch, roll, and depth of the cable transmitter.

Viewing Transmitter Depth or Predicted Depth

The depth or predicted depth of the transmitter can also be viewed on the remote display. The receiver must be positioned over either the locate line (LL) or one of the locate points (FLP or RLP) for this function to work—see “Locate Points (FLP & RLP) and Locate Line (LL)” in the *Locating* section. Also, this function is only available on Eclipse systems produced after February 2002.

Once the receiver is positioned over the LL, FLP, or RLP, the receiver operator holds in the trigger to take the depth or predicted depth reading. The remote display will emit a single tone to notify the operator that the depth information is being displayed. This depth/predicted depth information will remain on the remote display’s screen for 10 seconds *or* as long as the receiver’s trigger is held in.

Viewing Status of Cable System Power Source

The battery status of the power source will display at the bottom of the remote display screen where the transmitter battery status normally displays. When the battery status symbol appears 100% full, the battery is delivering at least 16 V of power. When the symbol is 50% full, the battery power is 14.5 V. When the symbol appears to be 25% full, the battery power is 14.0 V.

NOTE: If the power source is delivering less than 9.7 V, the system will automatically shut off.

Target Steering Function Using the Cable System

The *Target Steering* function can be used with the Eclipse cable system. In fact, the feasible steering distance with the cable transmitter is greater than it is with the battery-operated transmitters. With the cable transmitter, the maximum horizontal distance over which you can program the transmitter is 50 ft (15.2 m), as opposed to 35 ft (10.7 m) with battery-operated transmitters. Please refer to the previous section, entitled *The Target Steering Function*, for instructions on programming target depth.

The feasible steering area when using the cable system is shown below.

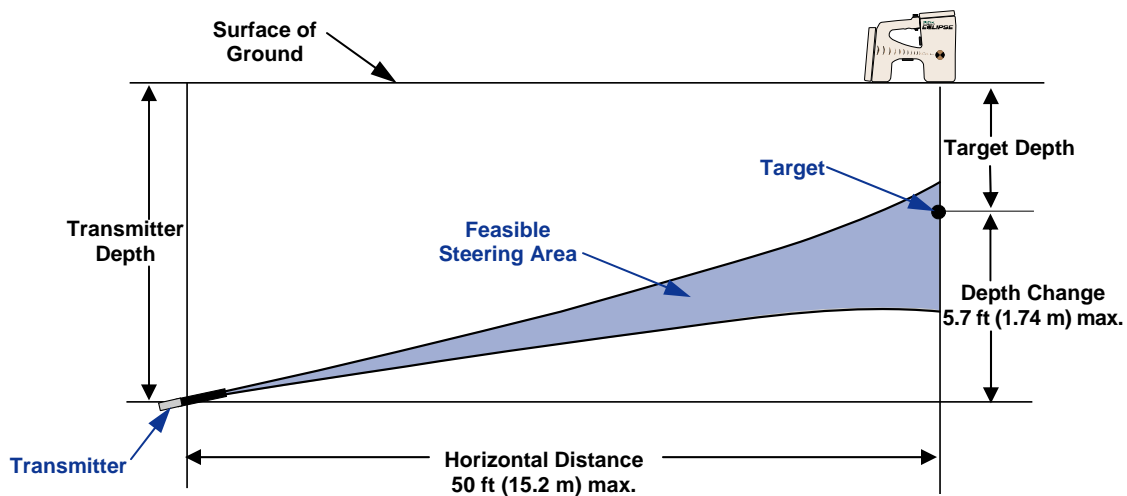


Diagram of Feasible Steering Area for Cable System

Maximum depth change is approximately 5.7 ft (1.74 m) over horizontal distance of 50 ft (15.2 m).



Notes

Troubleshooting

If you have a problem with your Eclipse locating system, review this section to see if you can find the probable cause and a remedy for the problem. If you cannot resolve your problem, then call DCI's Customer Service Department (425-251-0559 or 800-288-3610) and we'll help you find a solution.

<i>Problem</i>	<i>Cause / Remedy</i>
<i>Eclipse Receiver</i>	
LL will not display	Position the receiver over one of the two locate points and hold in the trigger for at least one second, then release the trigger. The reference "R" should display at the top of the locate screen and the LL should come up.
Depth information seems inaccurate	The elevation of the receiver above the tool has changed while the trigger was being held in. Release the trigger, position the receiver wherever you would like to take a depth reading and then hold in the trigger while keeping the receiver at a constant elevation.
Depth is greater than expected	The receiver is set to the wrong frequency setting. Exit to main menu and change the frequency setting. Return to locate screen and take another depth reading. (For more information, see "Changing the Frequency Setting" in the <i>Receiver</i> section.)
Display shows "Recal Tilt" message dialog box	The receiver battery may be low. Select "N" for No in the dialog box and replace battery. If you selected "Y" for Yes, call DCI Customer Service.
Target moves erratically on display	Contact DCI Customer Service.
Target does not remain in box on display when receiver is rotated	The receiver's antenna may be malfunctioning. Contact DCI Customer Service for assistance.
It is difficult to get LL to line up with horizontal cross hairs	This situation usually occurs when the receiver is placed above rebar. Try lifting the receiver up as high as possible. If holding the receiver higher doesn't help, try taking a step either forward or backward. Then align the LL to the top or bottom of the Eclipse icon rather than the cross hair through the center of the icon.
Display goes blank	The screen contrast may have accidentally been adjusted. If so, push the toggle to the right or left several times (at least 8–10) while clicking the trigger. Try changing the transmitter's battery.
Display goes dark	The screen contrast may need to be adjusted. To adjust the contrast, hold in the trigger and repetitively push the toggle to the right or left. The contrast can also be adjusted by holding the toggle in either the left position or the right position while clicking the trigger.
Display locks up or becomes erratic	The NiCad battery is probably dead. Replace the battery with a fully charged battery, and click the trigger to power up the unit.
Transmitter battery status icon does not display battery status	Turn receiver off and then back on. Go back into the locate mode and hold the trigger to view the transmitter battery icon with status bars inside. Change the transmitter's battery.
Pitch, roll, temperature, and/or transmitter battery status blinks	Move receiver closer to transmitter. Move receiver away from potential interference sources.

Problem	Cause / Remedy
Eclipse Receiver (cont.)	
Pitch, roll, or depth information is different than on remote display	<p>Receiver and remote display may be set to different channels or may be using different measurement settings. Verify that both units are set to the same channel, are set to the same grade mode, and are set to the same depth measurement mode.</p> <p>If you confirm that all settings are the same on both devices and there is still a problem, then try using a different channel.</p>

Eclipse Remote Display	
Display goes blank	<p>The screen contrast may have accidentally been adjusted. If so, push the right or left toggle arrow several times (at least 8–10) while pushing in the execute button, or push in the right or left toggle arrow while repetitively pushing the execute button.</p> <p>Try changing the transmitter's battery.</p>
Display goes dark	<p>The screen contrast may need to be adjusted. To adjust the contrast, push in the execute button while repetitively pushing the right or left toggle arrow, or push the left or right toggle arrow in while repetitively pushing the execute button.</p>
Display locks up	<p>The NiCad battery is probably dead. Replace the battery with a fully charged battery, and press the execute button to power up the unit.</p>
Display will not turn on	<p>The battery is not properly installed. Insert battery so that the two exposed terminals make contact with the bottom two springs in the remote display's battery compartment.</p> <p>The battery voltage is too low. Replace battery.</p>
Display will not show depth	<p>Software version in remote is earlier than February 2002. Call DCI to upgrade your software.</p>
Update indicator stops rotating	<p>Receiver is not in locate mode and, therefore, is not sending data to the remote display. NOTE: The receiver must be in locate mode to send signals to the remote display.</p> <p>Remote is not receiving information from the receiver. Try repositioning the receiver and/or the remote so that there is less interference between them.</p>
Pitch, roll, or depth information is different than on the receiver	<p>Receiver and remote display may be set to different channels or may be using different measurement settings. Verify that both units are set to the same channel, are set to the same grade mode, and are set to the same depth measurement mode.</p> <p>If you confirm that all settings are the same on both devices and there is still a problem, then try using a different channel.</p>
Pitch, roll, temperature, and/or transmitter battery status blinks	<p>Move receiver closer to transmitter.</p> <p>Move receiver and/or remote display away from potential interference sources.</p>
Steer-to target disappears	<p>Place the receiver above the FLP, RLP, or LL and hold in the trigger. This will reset the remote display screen to <i>Target Steering</i> mode.</p>
Loss of data	<p>Verify that the receiver and remote display are set to the same channel and that the Tele Option or TLT settings are correct.</p> <p>From the receiver, exit locate mode and then go back into locate mode.</p>

Appendix

The information and tables contained in this appendix provide further assistance for confirming the position of the Transmitter. The following information is provided:

Depth Increase in Inches (Centimeters) per 6-foot (1.8 meter) Rod

Depth Increase in Inches (Centimeters) per 10-foot (3-meter) Rod

Depth Increase in Inches (Centimeters) per 15-foot (4.6-meter) Rod

Percent of Grade to Degree Conversions (0.1% Pitch Transmitters or Sensitive Pitch)

Degree to Percent of Grade Conversions (0.1% Pitch Transmitters)

Calculating Depth Based on Distance Between FLP and RLP

Depth Increase in Inches (Centimeters) per 6-foot (1.8 meter) Rod

Percent	Depth Increase		Percent	Depth Increase
1	0.6 (1.5)		28	16.8 (42.7)
2	1.2 (3.0)		29	17.4 (44.2)
3	1.8 (4.6)		30	18.0 (45.7)
4	2.4 (6.1)		31	18.6 (47.2)
5	3.0 (7.6)		32	19.2 (48.8)
6	3.6 (9.1)		33	19.8 (50.3)
7	4.2 (10.7)		34	20.4 (51.8)
8	4.8 (12.2)		35	21.0 (53.3)
9	5.4 (13.7)		36	21.6 (54.9)
10	6.0 (15.2)		37	22.2 (56.4)
11	6.6 (16.8)		38	22.8 (57.9)
12	7.2 (18.3)		39	23.4 (59.4)
13	7.8 (19.8)		40	24.0 (61.0)
14	8.4 (21.3)		41	24.6 (62.5)
15	9.0 (22.9)		42	25.2 (64.0)
16	9.6 (24.4)		43	25.8 (65.5)
17	10.2 (25.9)		44	26.4 (67.1)
18	10.8 (27.4)		45	27.0 (68.6)
19	11.4 (29.0)		46	27.6 (70.1)
20	12.0 (30.5)		47	28.2 (71.6)
21	12.6 (32.0)		50	30.0 (76.2)
22	13.2 (33.5)		55	33.0 (83.8)
23	13.8 (35.1)		60	36.0 (91.4)
24	14.4 (36.6)		70	42.0 (106.7)
25	15.0 (38.1)		80	48.0 (121.9)
26	15.6 (39.6)		90	54.0 (137.2)
27	16.2 (41.1)		100	60.0 (152.4)

Depth Increase in Inches (Centimeters) per 10-foot (3-meter) Rod

Percent	Depth Increase		Percent	Depth Increase
1	1 (2)		28	32 (81)
2	2 (5)		29	33 (84)
3	4 (10)		30	34 (86)
4	5 (13)		31	36 (91)
5	6 (15)		32	37 (94)
6	7 (18)		33	38 (97)
7	8 (20)		34	39 (99)
8	10 (25)		35	40 (102)
9	11 (28)		36	41 (104)
10	12 (30)		37	42 (107)
11	13 (33)		38	43 (109)
12	14 (36)		39	44 (112)
13	15 (38)		40	45 (114)
14	17 (43)		41	46 (117)
15	18 (46)		42	46 (117)
16	19 (48)		43	47 (119)
17	20 (51)		44	48 (122)
18	21 (53)		45	49 (124)
19	22 (56)		46	50 (127)
20	24 (61)		47	51 (130)
21	25 (64)		50	54 (137)
22	26 (66)		55	58 (147)
23	27 (69)		60	62 (157)
24	28 (71)		70	69 (175)
25	29 (74)		80	75 (191)
26	30 (76)		90	80 (203)
27	31 (79)		100	85 (216)

Depth Increase in Inches (Centimeters) per 15-foot (4.6-meter) Rod

Percent	Depth Increase		Percent	Depth Increase
1	2 (5)		28	49 (124)
2	4 (10)		29	50 (127)
3	5 (13)		30	52 (132)
4	7 (18)		31	53 (135)
5	9 (23)		32	55 (140)
6	11 (28)		33	56 (142)
7	13 (33)		34	58 (147)
8	14 (36)		35	59 (150)
9	16 (41)		36	61 (155)
10	18 (46)		37	62 (157)
11	20 (51)		38	64 (163)
12	21 (53)		39	65 (165)
13	23 (58)		40	67 (170)
14	25 (64)		41	68 (173)
15	27 (69)		42	70 (178)
16	28 (71)		43	71 (180)
17	30 (76)		44	72 (183)
18	32 (81)		45	74 (188)
19	34 (86)		46	75 (191)
20	35 (89)		47	77 (196)
21	37 (94)		50	80 (203)
22	39 (99)		55	87 (221)
23	40 (102)		60	93 (236)
24	42 (107)		70	103 (262)
25	44 (112)		80	112 (284)
26	45 (114)		90	120 (305)
27	47 (119)		100	127 (323)

Percent of Grade to Degree Conversions (0.1% Pitch Transmitters or Sensitive Pitch)

Percent	Degree	Percent	Degree	Percent	Degree	Percent	Degree
0.1	0.1	2.6	1.5	5.1	2.9	7.6	4.3
0.2	0.1	2.7	1.5	5.2	3.0	7.7	4.4
0.3	0.2	2.8	1.6	5.3	3.0	7.8	4.5
0.4	0.2	2.9	1.7	5.4	3.1	7.9	4.5
0.5	0.3	3	1.7	5.5	3.1	8	4.6
0.6	0.3	3.1	1.8	5.6	3.2	8.1	4.6
0.7	0.4	3.2	1.8	5.7	3.3	8.2	4.7
0.8	0.5	3.3	1.9	5.8	3.3	8.3	4.7
0.9	0.5	3.4	1.9	5.9	3.4	8.4	4.8
1	0.6	3.5	2.0	6	3.4	8.5	4.9
1.1	0.6	3.6	2.1	6.1	3.5	8.6	4.9
1.2	0.7	3.7	2.1	6.2	3.5	8.7	5.0
1.3	0.7	3.8	2.2	6.3	3.6	8.8	5.0
1.4	0.8	3.9	2.2	6.4	3.7	8.9	5.1
1.5	0.9	4	2.3	6.5	3.7	9	5.1
1.6	0.9	4.1	2.3	6.6	3.8	9.1	5.2
1.7	1.0	4.2	2.4	6.7	3.8	9.2	5.3
1.8	1.0	4.3	2.5	6.8	3.9	9.3	5.3
1.9	1.1	4.4	2.5	6.9	3.9	9.4	5.4
2	1.1	4.5	2.6	7	4.0	9.5	5.4
2.1	1.2	4.6	2.6	7.1	4.1	9.6	5.5
2.2	1.3	4.7	2.7	7.2	4.1	9.7	5.5
2.3	1.3	4.8	2.7	7.3	4.2	9.8	5.6
2.4	1.4	4.9	2.8	7.4	4.2	9.9	5.7
2.5	1.4	5	2.9	7.5	4.3	10	5.7

Degree to Percent of Grade Conversions (0.1% Pitch Transmitters)

Degrees	Percent		Degrees	Percent
0.1	0.2		3.1	5.4
0.2	0.3		3.2	5.6
0.3	0.5		3.3	5.8
0.4	0.7		3.4	5.9
0.5	0.9		3.5	6.1
0.6	1.0		3.6	6.3
0.7	1.2		3.7	6.5
0.8	1.4		3.8	6.6
0.9	1.6		3.9	6.8
1	1.7		4	7.0
1.1	1.9		4.1	7.2
1.2	2.1		4.2	7.3
1.3	2.3		4.3	7.5
1.4	2.4		4.4	7.7
1.5	2.6		4.5	7.9
1.6	2.8		4.6	8.0
1.7	3.0		4.7	8.2
1.8	3.1		4.8	8.4
1.9	3.3		4.9	8.6
2	3.5		5	8.7
2.1	3.7		5.1	8.9
2.2	3.8		5.2	9.1
2.3	4.0		5.3	9.3
2.4	4.2		5.4	9.5
2.5	4.4		5.5	9.6
2.6	4.5		5.6	9.8
2.7	4.7		5.7	10.0
2.8	4.9			
2.9	5.1			
3	5.2			

Calculating Depth Based on Distance Between FLP and RLP

It is possible to estimate the transmitter's depth should the information displayed in the depth/distance window become unreliable. This is only possible if the pitch and negative locate points are reliable and the ground surface is level.

To estimate the transmitter's depth, first measure the distance between the FLP and the RLP. The pitch of the transmitter must also be reliably known. Using the Depth Estimation Table below, find the divider that most closely corresponds to the transmitter's pitch. Then use the following formula to estimate the depth:

$$\text{Depth} = \frac{\text{Distance between FLP and RLP}}{\text{Divider}}$$

For example, if the transmitter's pitch is 34% then the corresponding divider value (from the table) is 1.50. In this example, the distance between the FLP and the RLP is 11.5 ft (3.5 m). The depth would be:

$$\text{Depth} = \frac{11.5 \text{ ft}}{1.50} = 7.66 \text{ ft or approximately } 7.7 \text{ ft (2.35 m)}$$

Depth Estimation Table

Pitch	Divider	Pitch	Divider	Pitch	Divider	Pitch	Divider
0	1.41	26	1.47	52	1.62	78	1.84
2	1.41	28	1.48	54	1.63	80	1.85
4	1.42	30	1.48	56	1.64	82	1.87
6	1.42	32	1.49	58	1.66	84	1.89
8	1.42	34	1.50	60	1.68	86	1.91
10	1.42	36	1.51	62	1.69	88	1.93
12	1.43	38	1.52	64	1.71	90	1.96
14	1.43	40	1.54	66	1.73	92	1.98
16	1.43	42	1.55	68	1.74	94	2.00
18	1.44	44	1.56	70	1.76	96	2.02
20	1.45	46	1.57	72	1.78	98	2.04
22	1.45	48	1.59	74	1.80	100	2.06
24	1.46	50	1.60	76	1.82		

Notes

3-1100-00-J

LIMITED WARRANTY

Digital Control Incorporated ("DCI") warrants that when shipped from DCI each DCI product ("DCI Product") will conform to DCI's current published specifications in existence at the time of shipment and will be free, for the warranty period ("Warranty Period") described below, from defects in materials and workmanship. The limited warranty described herein ("Limited Warranty") is not transferable, shall extend only to the first end-user ("User") purchasing the DCI Product from either DCI or a dealer expressly authorized by DCI to sell DCI Products ("Authorized DCI Dealer"), and is subject to the following terms, conditions and limitations:

1. A Warranty Period of twelve (12) months shall apply to the following new DCI Products: receivers/locators, remote displays, battery chargers and rechargeable batteries, and DataLog[®] modules and interfaces. A Warranty Period of ninety (90) days shall apply to all other new DCI Products, including transmitters, accessories, and software programs and modules. Unless otherwise stated by DCI, a Warranty Period of ninety (90) days shall apply to: (a) a used DCI Product sold either by DCI or by an Authorized DCI Dealer who has been expressly authorized by DCI to sell such used DCI Product; and (b) services provided by DCI, including testing, servicing, and repairing an out-of-warranty DCI Product. The Warranty Period shall begin from the later of: (i) the date of shipment of the DCI Product from DCI, or (ii) the date of shipment (or other delivery) of the DCI Product from an Authorized DCI Dealer to User.

2. DCI's sole obligation under this Limited Warranty shall be limited to either repairing, replacing, or adjusting, at DCI's option, a covered DCI Product that has been determined by DCI, after reasonable inspection, to be defective during the foregoing Warranty Period. All warranty inspections, repairs and adjustments must be performed either by DCI or by a warranty claim service authorized in writing by DCI. All warranty claims must include proof of purchase, including proof of purchase date, identifying the DCI Product by serial number.

3. The Limited Warranty shall only be effective if: (i) within fourteen (14) days of receipt of the DCI Product, User mails a fully-completed Product Registration Card to DCI; (ii) User makes a reasonable inspection upon first receipt of the DCI Product and immediately notifies DCI of any apparent defect; and (iii) User complies with all of the Warranty Claim Procedures described below.

WHAT IS NOT COVERED

This Limited Warranty excludes all damage, including damage to any DCI Product, due to: failure to follow DCI's user's manual and other DCI instructions; abuse; misuse; neglect; accident; fire; flood; Acts of God; improper applications; connection to incorrect line voltages and improper power sources; use of incorrect fuses; overheating; contact with high voltages or injurious substances; or other events beyond the control of DCI. This Limited Warranty does not apply to any equipment not manufactured or supplied by DCI nor, if applicable, to any damage or loss resulting from use of any DCI Product outside the designated country of use. By accepting a DCI Product and not returning it for a refund within thirty (30) days of purchase, User agrees to the terms of this Limited Warranty, including without limitation the Limitation of Remedies and Liability described below, and agrees to carefully evaluate the suitability of the DCI Product for User's intended use and to thoroughly read and strictly follow all instructions supplied by DCI (including any updated DCI Product information which may be obtained at the above DCI website). In no event shall this Limited Warranty cover any damage arising during shipment of the DCI Product to or from DCI.

User agrees that the following will render the above Limited Warranty void: (i) alteration, removal or tampering with any serial number, identification, instructional, or sealing labels on the DCI Product, or (ii) any unauthorized disassembly, repair or modification of the DCI Product. In no event shall DCI be responsible for the cost of or any damage resulting from any changes, modifications, or repairs to the DCI Product not expressly authorized in writing by DCI, and DCI shall not be responsible for the loss of or damage to the DCI Product or any other equipment while in the possession of any service agency not authorized by DCI.

DCI reserves the right to make changes in design and improvements upon DCI Products from time to time, and User understands that DCI shall have no obligation to upgrade any previously manufactured DCI Product to include any such changes.

The foregoing Limited Warranty is DCI's sole warranty and is made in place of all other warranties, express or implied, including but not limited to the implied warranties of merchantability and fitness for a particular purpose and any implied warranty arising from course of performance, course of dealing, or usage of trade. If DCI has substantially complied with the warranty claim procedures described below, such procedures shall constitute User's sole and exclusive remedy for breach of the Limited Warranty.

LIMITATION OF REMEDIES AND LIABILITY

In no event shall DCI nor anyone else involved in the creation, production, or delivery of the DCI Product be liable for any damages arising out of the use or inability to use the DCI Product, including but not limited to indirect, special, incidental, or consequential damages or for any cover, loss of information, profit, revenue or use based upon any claim by User for breach of warranty, breach of contract, negligence, strict liability, or any other legal theory, even if DCI has been advised of the possibility of such damages. In no event shall DCI's liability exceed the amount User has paid for the DCI Product. To the extent that any applicable law does not allow the exclusion or limitation of incidental, consequential or similar damages, the foregoing limitations regarding such damages shall not apply.

This Limited Warranty gives you specific legal rights, and you may also have other rights which vary from state to state. This Limited Warranty shall be governed by the laws of the State of Washington.

WARRANTY CLAIM PROCEDURES

1. If you are having problems with your DCI Product, you must first contact the Authorized DCI Dealer where it was purchased. If you are unable to resolve the problem through your Authorized DCI Dealer, contact DCI's Customer Service Department in Kent, Washington, USA at the above telephone number between 6:00 a.m. and 6:00 p.m. Pacific Time and ask to speak with a customer service representative. (The above "800" number is available for use only in the USA and Canada.) Prior to returning any DCI Product to DCI for service, you must obtain a Return Merchandise Authorization (RMA) number. Failure to obtain a RMA may result in delays or return to you of the DCI Product without repair.
2. After contacting a DCI customer service representative by telephone, the representative will attempt to assist you in troubleshooting while you are using the DCI Product during actual field operations. Please have all related equipment available together with a list of all DCI Product serial numbers. It is important that field troubleshooting be conducted because many problems do not result from a defective DCI Product, but instead are due to either operational errors or adverse conditions occurring in the User's drilling environment.
3. If a DCI Product problem is confirmed as a result of field troubleshooting discussions with a DCI customer service representative, the representative will issue a RMA number authorizing the return of the DCI Product and will provide shipping directions. You will be responsible for all shipping costs, including any insurance. If, after receiving the DCI Product and performing diagnostic testing, DCI determines the problem is covered by the Limited Warranty, required repairs and/or adjustments will be made, and a properly functioning DCI Product will be promptly shipped to you. If the problem is not covered by the Limited Warranty, you will be informed of the reason and be provided an estimate of repair costs. If you authorize DCI to service or repair the DCI Product, the work will be promptly performed and the DCI Product will be shipped to you. You will be billed for any costs for testing, repairs and adjustments not covered by the Limited Warranty and for shipping costs. In most cases, repairs are accomplished within 1 to 2 weeks.
4. DCI has a limited supply of loaner equipment available. If loaner equipment is required by you and is available, DCI will attempt to ship loaner equipment to you by overnight delivery for your use while your equipment is being serviced by DCI. DCI will make reasonable efforts to minimize your downtime on warranty claims, limited by circumstances not within DCI's control. If DCI provides you loaner equipment, your equipment must be received by DCI no later than the second business day after your receipt of loaner equipment. You must return the loaner equipment by overnight delivery for receipt by DCI no later than the second business day after your receipt of the repaired DCI Product. Any failure to meet these deadlines will result in a rental charge for use of the loaner equipment for each extra day the return of the loaner equipment to DCI is delayed.